Overview



With its world headquarters located in Orchard Park, New York, USA, ITT ENIDINE Inc. is a world leader in the design and manufacture of standard and custom energy absorption and vibration isolation product solutions within the Industrial, Aerospace, Defense, Marine and Rail markets. Product ranges include shock absorbers, gas springs, rate controls, air springs, wire rope isolators, heavy industry buffers and emergency stops. With facilities strategically located throughout the world and in partnership with our vast global network of distributors, Enidine Incorporated continues to strengthen its presence within marketplace.

Founded in 1966, ITT Enidine Incorporated now has close to 600 employees located throughout the globe in the United States, Germany, France, Japan, China and Korea. With a team of professionals in engineering, computer science, manufacturing, production and marketing our employees provide our customers the very best in service and application solutions.

"ITT Enidine is widely recognized as the preferred source for energy absorption and vibration isolation products."

From Original Equipment Manufacturers (OEM) to aftermarket applications, ITT Enidine offers a unique combination of product selection, engineering excellence and technical support to meet even the toughest energy absorption application requirements.

Global Manufacturing and Sales Facilities offer our customers:

- Highly Trained Distribution Network
- State-of-the Art Engineering Capabilities
- Custom Solution Development
- Customer Service Specialists
- Multiple Open Communication Channels

If you are unsure whether one of our standard products meets your requirements, feel free to speak with one of our technical representatives toll-free at 1-800-852-8508, or contact us via e-mail at techsales@enidine.com.

Products/Engineering/Technical Support

ITT Enidine continually strives to provide the widest selection of shock absorbers and rate control products in the global marketplace. Through constant evaluation and testing, we bring our customers the most cost effective products with more features, greater performance and improved ease of use.

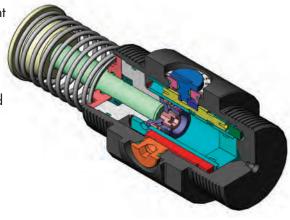
New Technologies and Enhancements

Research and Development

New Products and Services

ITT Enidine engineers continue to monitor and influence trends in the motion control industry, allowing us to remain at the forefront of new energy absorption product development such as our new ECO Series shock absorbers and our new HDN Series shock Absorbers.

Our experienced engineering team has designed custom solutions for a wide variety of challenging applications, including automated warehousing systems and shock absorbers for hostile industrial environments such as glass manufacturing, among others. These custom application solutions have proven to be critical to our customers' success. Let ITT Enidine engineers do the same for you.





Custom designs are not an exception at ITT Enidine, they are an integral part of our business. Should your requirements fit outside of our standard product range, Enidine engineers can assist in developing special finishes, components, hybrid technologies and new designs to ensure a "best-fit" product solution customized to your exact specifications.

A talented engineering staff works to design and maintain the most efficient energy absorption product lines available today, using the latest engineering tools:

- Solid Modeling
- 3-D CAD Drawings
- 3-D Soluable Support Technology
- Finite Element Analysis
- Complete Product Verification Testing Facility

New product designs get to market fast because they can be fully developed in virtual environments before a prototype is ever built. This saves time and lets us optimize the best solution using real performance criteria.

Global Service and Support

ITT Enidine offers its customers a global network of customer service staff technical sales personnel that are available to assist you with all of your application needs.

- Operating with lean manufacturing and cellular production, ITT Enidine produces higher quality custom and standard products with greater efficiency and within shorter lead times.
- An authorized Global Distribution Network is trained regularly by ITT Enidine staff on new products and services ensuring they are better able to serve you.
- New Enisize sizing portal provides our customer with the necessary sizing and design tools. www.enisize.com
- Global operations in United States, Germany, France, China, Japan and Korea.
- A comprehensive, website full of application information, technical data, sizing examples and information to assist in selecting the product that's right for you.

Our website also features a searchable worldwide distributor lookup to help facilitate fast, localized service. Contact us today for assistance with all of your application needs.

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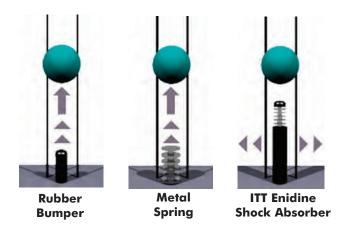
Our global customer service and technical sales departments are available to assist you find the solution that's right for your application needs. Call us at 1.800.852.8508 or e-mail us at industrialsales@enidine.com and let us get started today.

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Theory of Energy Absorption

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As companies strive to increase productivity by operating machinery at higher speeds, often the results are increased noise, damage to machinery/products, and excessive vibration. At the same time, safety and machine reliability are decreased. A variety of products are commonly used to solve these problems. However, they vary greatly in effectiveness and operation. Typical products used include rubber bumpers, springs, cylinder cushions and shock absorbers. The following illustrations compare how the most common products perform:

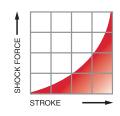


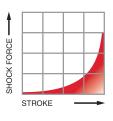
All moving objects possess kinetic energy. The amount of energy is dependent upon weight and velocity. A mechanical device that produces forces diametrically opposed to the direction of motion must be used to bring a moving object to rest.

Rubber bumpers and springs,

although very inexpensive, have an undesirable recoil effect. Most of the energy absorbed by these at impact is actually stored. This stored energy is returned to the load, producing rebound and the potential for damage to the load or machinery. Rubber bumpers and springs initially provide low resisting force which increases with the stroke.

Cylinder cushions are limited in their range of operation. Most often they are not capable of absorbing energy generated by the system. By design, cushions have a relatively short stroke and operate at low pressures resulting in very low energy absorption. The remaining energy is transferred to the system, causing shock loading and vibration.





Shock absorbers provide controlled, predictable deceleration. These products work by converting kinetic energy to thermal energy. More specifically, motion applied to the piston of a hydraulic shock absorber pressurizes the fluid and forces it to flow through restricting orifices, causing the fluid to heat rapidly. The thermal energy is then transferred to the cylinder body and harmlessly dissipated to the atmosphere.

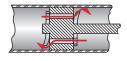
Overview

The advantages of using shock absorbers include:

- 1. Longer Machine Life The use of shock absorbers significantly reduces shock and vibration to machinery. This eliminates machinery damage, reduces downtime and maintenance costs, while increasing machine life.
- **2.** Higher Operating Speeds Machines can be operated at higher speeds because shock absorbers control or gently stop moving objects. Therefore, production rates can be increased.
- **3.** Improved Production Quality Harmful side effects of motion, such as noise, vibration and damaging impacts, are moderated or eliminated so the quality of production is improved. Therefore, tolerances and fits are easier to maintain.
- **4. Safer Machinery Operation** Shock absorbers protect machinery and equipment operators by offering predictable, reliable and controlled deceleration. They can also be designed to meet specified safety standards, when required.
- **5. Competitive Advantage** Machines become more valuable because of increased productivity, longer life, lower maintenance costs and safer operation.

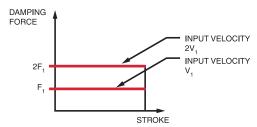
Automotive vs. Industrial Shock Absorbers

It is important to understand the differences that exist between the standard automotive-style shock absorber and the industrial shock absorber.

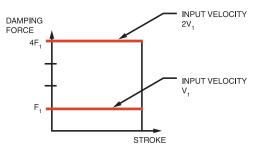


DEFLECTIVE BEAM ORIFICE

The automotive style employs the deflective beam and washer method of orificing. Industrial shock absorbers utilize single orifice, multi-orifice and metering pin configurations. The automotive type maintains a damping force which varies in direct proportion to the velocity of the piston, while the damping force in the industrial type varies in proportion to the square of the piston velocity. In addition, the damping force of the automotive type is independent of the stroke position while the damping force associated with the industrial type can be designed either dependent or independent of stroke position.



AUTOMOTIVE TYPE SHOCK ABSORBER



INDUSTRIAL TYPE SHOCK ABSORBER



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Theory of Energy Absorption

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Equally as important, automotive-style shock absorbers are designed to absorb only a specific amount of input energy. This means that, for any given geometric size of automotive shock absorber, it will have a limited amount of absorption capability compared to the industrial type.

This is explained by observing the structural design of the automotive type and the lower strength of materials commonly used. These materials can withstand the lower pressures commonly found in this type. The industrial shock absorber uses higher strength materials, enabling it to function at higher damping forces.

Adjustment Techniques

A properly adjusted shock absorber safely dissipates energy, reducing damaging shock loads and noise levels. For optimum adjustment setting see useable adjustment setting graphs. Watching and "listening" to a shock absorber as it functions aids in proper adjustment.



Damping Force

To correctly adjust a shock absorber, set the adjustment knob at zero (0) prior to system engagement. Cycle the mechanism and observe deceleration of the system.

If damping appears too soft (unit strokes with no visual deceleration and bangs at end of stroke), move indicator to next largest number. Adjustments must be made in gradual increments to avoid internal damage to the unit (e.g., adjust from 0 to 1, not 0 to 4).

Increase adjustment setting until smooth deceleration or control is achieved and negligible noise is heard when the system starts either to decelerate or comes to rest.

When abrupt deceleration occurs at the beginning of the stroke (banging at impact), the adjustment setting must be moved to a lower number to allow smooth deceleration.

If the shock absorber adjustment knob is set at the high end of the adjustment scale and abrupt deceleration occurs at the end of the stroke, a larger unit may be required.

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Overview

Shock Absorber Performance When Weight or Impact Velocity Vary

When conditions change from the original calculated data or actual input, a shock absorber's performance can be greatly affected, causing failure or degradation of performance. Variations in input conditions after a shock absorber has been installed can cause internal damage, or at the very least, can result in unwanted damping performance. Variations in weight or impact velocity can be seen by examining the following energy curves:

Varying Impact Weight: Increasing the impact weight (impact velocity remains unchanged), without reorificing or readjustment will result in increased damping force at the end of the stroke. Figure 1 depicts this undesirable bottoming peak force. This force is then transferred to the mounting structure and impacting load.

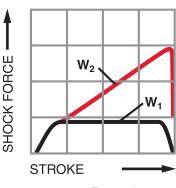
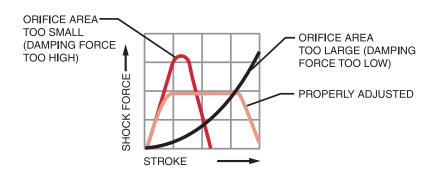


Figure 1

Varying Impact Velocity: Increasing impact velocity (weight remains the same) results in a radical change in the resultant shock force. Shock absorbers are velocity conscious products; therefore, the critical relationship to impact velocity must be carefully monitored. Figure 2 depicts the substantial change in shock force that occurs when the velocity is increased. Variations from original design data or errors in original data may cause damage to mounting structures and systems, or result in shock absorber failure if the shock force limits are exceeded.



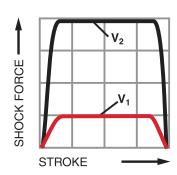


Figure 2

4

Typical Shock Absorber Applications

SHOCK ABSORBER SIZING

Follow the next six steps to manually size Enidine shock absorbers:

STEP 1: Identify the following parameters. These must be known for all energy absorption calculations. Variations or additional information may be required in

A. Weight of the load to be stopped (lbs.)(Kg).

B. Velocity of the load upon impact with the shock absorber (in./sec.)(m/s).

C. External (propelling) forces acting on the load (lbs.)(N), if any.

D. Cyclic frequency at which the shock absorber will operate.

E. Orientation of the application's motion (i.e. horizontal, vertical up, vertical down, inclined, rotary horizontal, rotary vertical up, rotary vertical down)

NOTE: For rotary applications, it is necessary to determine both the radius of gyration (K) and the mass moment of inertia (I). Both of these terms locate the mass of a rotating object with respect to the pivot point. It is also necessary to determine the angular velocity (ω) and the torque (T).

STEP 2: Calculate the kinetic energy of the moving object.

$$E_K = \frac{W}{772} \times V^2$$
 (linear) or $E_K = \frac{I}{2} \omega^2$ (rotary) or $E_K = \frac{1}{2} MV^2$ (metric)

(Note: $772 = 2 \times acceleration due to gravity)$

Utilizing the Product Locators for Shock Absorbers located at the beginning of each product family section, select a model, either adjustable or non-adjustable, with a greater energy per cycle capacity than the value just calculated.

STEP 3: Calculate the work energy input from any external (propelling) forces acting on the load, using the stroke of the model selected in Step 2.

$$E_W = F_D \times S$$
 (linear) or $E_W = \frac{T}{R_S} \times S$ (rotary)

Caution: The propelling force must not exceed the maximum propelling force listed for the model chosen. If the propelling force is too high, select a larger model and recalculate the work energy.

STEP 4: Calculate the total energy per cycle $E_T = E_K + E_W$

The model selected must have at least this much energy capacity. If not, select a model with greater energy capacity and return to Step 3.

STEP 5: Calculate the energy that must be absorbed per hour. Even though the shock absorber can absorb the energy in a single impact, it may not be able to dissipate the heat generated if the cycle rate is too high.

$$E_TC = E_T \times C$$

The model selected must have an energy per hour capacity greater than this calculated figure. If it is not greater, there are two options:

1. Choose another model that has more energy per hour capacity (because of larger diameter or stroke). Keep in mind that if the stroke changes, you must return to Step 3.

2. Use an Air/Oil Tank. The increased surface area of the tank and piping will increase the energy per hour capacity by 20 percent.

STEP 6: If you have selected an HP, PM, SPM, TK, or PRO Series model, refer to the sizing graph(s) in the appropriate series section to determine the required damping constant. If the point cannot be found in the sizing graph, you must select a larger model or choose a different series. Note that if the stroke changes, you must return to Step 3.

If you have selected an adjustable model (OEM, HP or HDA series), refer to the Useable Adjustment Setting Range graph for the chosen model. The impact velocity must fall within the limits shown on the graph.

Overview

RATE CONTROL SIZING

Follow the next five steps to manually size ITT Enidine rate controls:

STEP 1: Identify the following parameters. These must be known for all rate control calculations. Variations or additional information may be required in some cases.

A. Weight of the load to be controlled (lbs.)(Kg) B. Desired velocity of the load (in/sec.)(m/s)

External (propelling) force acting on the

load (lbs.)(N), if any.

D. Cyclic frequency at which the rate control will operate.

E. Orientation of the application's motion (i.e. horizontal, vertical up, vertical down, inclined, rotary horizontal, rotary vertical up, rotary vertical down.)

Damping direction (i.e., tension [T], compression [C] or both [T and C].

G. Required stroke (in.)(mm)

STEP 2: Calculate the propelling force at the rate control in each direction damping is required. (See sizing examples on page 6-12). CAUTION: The propelling force in each direction must not exceed the maximum propelling force listed for the chosen model. If the propelling force is too high, select a larger model.

STEP 3: Calculate the total energy per cycle $E_T = E_W$ (tension) + E_W (compression) $E_W = F_D \times S$

STEP 4: Calculate the total energy per hour $E_TC = E_T \times C$

The model selected must have an energy per hour capacity greater than this calculated figure. If not, choose a model with a higher energy per hour capacity.

Compare the damping direction, stroke, propelling force, and total energy per hour to the values listed in the Rate Controls Engineering Data Charts (pages 97-106).

STEP 5: If you have selected a rate control, refer to the sizing graphs in the Rate Controls section to determine the required damping

If you have selected an adjustable model (ADA), refer to the Useable Adjustment Setting Range graph for the chosen model. The desired velocity must fall within the limits shown on the graph.

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Typical Shock Absorber Applications

SYMBOLS

 $a = Acceleration (in./sec.^2)(mls^2)$

A = Width (in.)(m)

B = Thickness (in.)(m)

C = Number of cycles per hour

d = Cylinder bore diameter (in.)(mm)

D = Distance (in.)(m)

 E_K = Kinetic energy (in-lbs.)(Nm) E_T = Total energy per cycle

(in-lbs./c)(Nm/c), $E_K + E_W$ $E_TC =$ Total energy to be absorbed per

hour (in-lbs./hr)(Nm/hr)

Ew = Work or drive energy (in-lbs.)(Nm)

 F_D = Propelling force (lbs.)(N) F_P = Shock force (lbs.)(N)

H = Height (in.)(m)

Hp = Motor rating (hp)(kw)

 I = Mass moment of inertia (in-lbs./sec²)(Kgm²)

K = Radius of gyration (in.)(m)

L = Length (in.)(m)

P = Operating pressure (psi)(bar)

R_S = Mounting distance from pivot point (in.)(m)

S = Stroke of shock absorber (in.)(m)

t = Time (sec.)

T = Torque (in-lbs.)(Nm)

V = Impact velocity (in./sec.)(m/s)

W = Weight (lbs.)(Kg)

 α = Angle of incline (degrees)

 θ = Start point from true vertical 0° (degrees)

 μ = Coefficient of friction

 \emptyset = Angle of rotation (degrees)

= Angular velocity (radians/sec)

USEFUL FORMULAS

1. To Determine Shock Force

$$F_P = \frac{E_T}{S \times .85}$$

For PRO and PM Series only, use

$$F_P = \frac{E_T}{S \times .50}$$

2. To Determine Impact Velocity

A. If there is no acceleration (V is constant) (e.g., load being $V = \frac{D}{t}$ pushed by hydraulic cylinder or motor driven.)

B. If there is acceleration.
(e.g., load being pushed by air cylinder)

V = 2 x t

3. To Determine Propelling Force Generated by Electric Motor

$$F_D = \frac{19,800 \times Hp}{V}$$
 $F_D = \frac{3000 \times Hp}{V}$ (metric)

Overview

4. To Determine Propelling Force of Pneumatic or Hydraulic Cylinders

 $F_D = .7854 \times d^2 \times P$ $F_D = 0.07854 \times d^2 \times P$ (metric)

5. Free Fall Applications

A. Find Velocity for a Free Falling Weight: $V = \sqrt{772} \times H$ $V = \sqrt{19,6} \times H$ (metric)

B. Kinetic Energy of Free Falling Weight: $E_K = W \times H$

6. Deceleration and G Load

A. To Determine Approximate G Load with a Given Stroke

 $G = \frac{F_P - F_D}{W}$ $G = \frac{F_P - F_D}{kg \times 9,81}$ (metric)

B. To Determine the Approximate Stroke with a Given G Load (Conventional Damping Only)

$$S = \frac{E_K}{GW.85 - .15 F_D}$$
PRO /PM and TK Mod

*For PRO/PM and TK Models:

$$S = \frac{E_K}{GW.5 - .5 F_D}$$

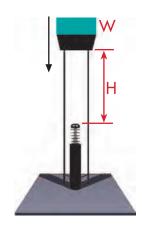
NOTE: Constants are printed in **bold**.

The following examples are shown using Imperial formulas and units of measure.

Shock Absorbers

EXAMPLE 1:

Vertical Free Falling Weight



STEP 1: Application Data

(W) Weight = 3,400 lbs. (H) Height = 20 in. (C) Cycles/Hr = 2

STEP 2: Calculate kinetic energy

 $E_K = W x H$

 $E_K = 3,400 \times 20 = 68,000 \text{ in-lbs.}$

Assume Model OEM 4.0M x 6 is adequate (Page 31).

STEP 3: Calculate work energy

 $E_W = W \times S$ $E_W = 3,400 \times 6$

 $E_W = 20,400 \text{ in-lbs.}$

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W$

 $E_T = 68,000 + 20,400$ $E_T = 88,400 \text{ in-lbs./c}$

STEP 5: Calculate total energy per hour

 $E_TC = E_T \times C$

 $E_TC = 88,400 \times 2$

 $E_TC = 176,800 \text{ in-lbs./hr}$

STEP 6: Calculate impact velocity and confirm selection

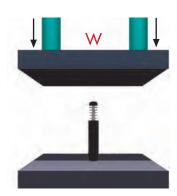
 $V = \sqrt{772 \times H}$

 $V = \sqrt{772 \times 20}$ V = 124 in./sec.

Model OEM 4.0M x 6 is adequate.

EXAMPLE 2:

Vertical Moving Load with Propelling Force Downward



STEP 1: Application Data

(W) Weight = 3,400 lbs.

(V) Velocity = 80 in./sec.

(d) Cylinder bore dia. = 4 in.

(P) Pressure = 70 psi

(C) Cycles/Hr = 200

STEP 2: Calculate kinetic energy

$$E_{K} = \frac{W}{772} \times V^{2} = \frac{3,400}{772} \times 80^{2}$$

 $E_{K} = 28,187 \text{ in-lbs.}$

Assume Model OEM 4.0M x 4 is adequate (Page 31).

STEP 3: Calculate work energy

 $F_D = [.7854 \times d^2 \times P] + W$

 $F_D = [.7854 \times 4^2 \times 70] + 3,400$

 $F_D = 4,280 \text{ lbs.}$

 $E_W = F_D \times S$

 $E_W = 4,280 \times 4$

 $E_W = 4,200 \text{ A}$ $E_W = 17,120 \text{ in-lbs.}$

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W$

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 $E_T = 28,187 + 17,120$ $E_T = 45,307 \text{ in-lbs./c}$

STEP 5: Calculate total energy per hour

 $E_TC = E_T \times C$

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 $E_TC = 45,307 \times 200$

 $E_TC = 45,307 \times 200$ $E_TC = 9,061,400 \text{ in-lbs./hr}$

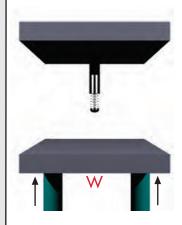
Model OEM 4.0M x 4 is adequate.

Typical Shock Absorber Applications

Overview

EXAMPLE 3:

Vertical Moving Load with **Propelling Force Upward**



STEP 1: Application Data

(W) Weight = 3,400 lbs. (V) Velocity = 80 in./sec.

(d) 2 Cylinders bore dia. = 6 in. (P) Operating pressure = 70 psi

(C) Cycles/Hr = 200

STEP 2: Calculate kinetic energy

$$E_K = \frac{W}{772} \times V^2 = \frac{3,400}{772} \times 80^2$$

 $E_K = 28,187 \text{ in-lbs.}$

Assume Model OEM 3.0M x 5 is adequate (Page 31).

STEP 3: Calculate work energy

 $F_D = 2 \times [.7854 \times d^2 \times P] - W$ $F_D = 2 \times [.7854 \times 6^2 \times 70] - 3,400$

 $F_D = 558 \text{ lbs.}$

 $E_W = F_D X S$

 $E_W = 558 \times 5$

 $E_W = 2,790 \text{ in-lbs.}$

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W$

 $E_T = 28,187 + 2,790$

 $E_T = 30,977 \text{ in-lbs./c}$

STEP 5: Calculate total energy per hour

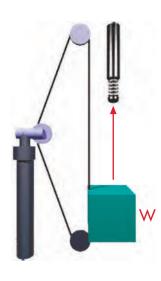
 $E_TC = E_T \times C$

 $E_TC = 30,977 \times 200$ $E_TC = 6,195,400 \text{ in-lbs./hr}$

Model OEM 3.0M x 5 is adequate.

EXAMPLE 4:

Vertical Moving Load with Propelling Force from Motor



STEP 1: Application Data

(W) Weight = 200 lbs.(V) Velocity = 60 in./sec. (Hp) Motor horsepower = 1.5 Hp (C) Cycles/Hr = 100

STEP 2: Calculate kinetic energy

$$E_K = \frac{W}{772} \times V^2 = \frac{200}{772} \times 60^2$$

 $E_K = 933 \text{ in-lbs.}$

CASE A: UP

STEP 3: Calculate work energy

$$F_D = \frac{19,800 \times Hp}{V} - W$$

$$F_D = \frac{19,800 \times 1.5}{60} - 200$$

 $F_D = 295 \text{ lbs.}$

Assume Model OEM 1.25 x 2 is adequate (Page 24).

 $E_W = F_D X S$

 $E_W = 295 \times 2$

 $E_W = 590 \text{ in-lbs.}$

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W$ $E_T = 933 + 590$ $E_T = 1,523 \text{ in-lbs./c}$

STEP 5: Calculate total energy per hour

 $E_TC = E_T \times C$

 $E_TC = 1,523 \times 100$ $E_TC = 152,300 \text{ in-lbs./hr}$

Model OEM 1.25 x 2 is adequate.

CASE B: DOWN

STEP 3: Calculate work energy

$$F_D = \frac{19,800 \times Hp}{V} + W$$

 $F_D = \frac{19,800 \times 1.5}{200} + 200$

 $F_D = 695 lbs.$

Assume Model OEMXT 2.0M x 2 is adequate (Page 29).

 $E_W = F_D \times S$

 $E_W = 695 \times 2$

 $E_W = 1,390$ in-lbs.

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W$ $E_T = 933 + 1,390$ $E_T = 2,323 \text{ in-lbs./c}$

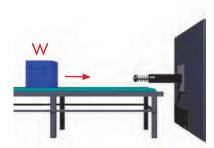
STEP 5: Calculate total energy per hour

 $E_TC = E_T \times C$ $E_TC = 2,323 \times 100$ $E_TC = 232,300 \text{ in-lbs./hr}$

Model OEMXT 2.0M x 2 is adequate.

(e.g., Load Moving Force Up)

EXAMPLE 5: Horizontal Moving Load



STEP 1: Application Data

(W) Weight = 1,950 lbs. (V) Velocity = 60 in./sec. (C) Cycles/Hr = 200

STEP 2: Calculate kinetic energy

$$E_K = \frac{W}{772} \times V^2$$

 $E_K = \frac{1950}{772} \times 60^2$
 $E_K = 9,093 \text{ in-lbs.}$

Assume Model OEMXT 2.0M x 2 is adequate (Page 29).

STEP 3: Calculate work energy: N/A

STEP 4: Calculate total energy per cycle

 $E_T = E_K = 9,093 \text{ in-lbs./c}$

STEP 5: Calculate total energy per hour

 $E_TC = E_T \times C$ $E_TC = 9,093 \times 200$ $E_TC = 1,818,600 \text{ in-lbs./hr}$

Model OEMXT 2.0M x 2 is adequate.

ENIDINE

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Tel.: 1-800-852-8508

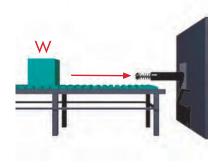
Fax: 1-716-662-0406

Typical Shock Absorber Applications

Overview

EXAMPLE 6:

Horizontal Moving Load with Propelling Force



STEP 1: Application Data

(W) Weight = 1,950 lbs. (V) Velocity = 60 in./sec.

(d) Cylinder bore dia. = 3 in.

(P) Operating pressure = 70 psi

STEP 2: Calculate kinetic energy

Assume Model OEMXT 2.0M x 2 is

(C) Cycles/Hr = 200

 $E_{K} = \frac{W}{772} \times V^{2}$

 $E_{K} = \frac{1,950}{772} \times 60^{2}$

 $E_{K} = 9,093 \text{ in-lbs.}$

adequate (Page 29).

 $F_D = .7854 \times d^2 \times P$ $F_D = .7854 \times 3^2 \times 70$

STEP 3: Calculate work energy

 $F_D = 495 lbs.$

 $E_W = F_D x S$

 $E_W = 495 \times 2$

 $E_W = 990$ in-lbs.

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W$

 $E_T = 9,093 + 990$

 $E_T = 10,083 \text{ in-lbs./c}$

STEP 5: Calculate total energy per hour

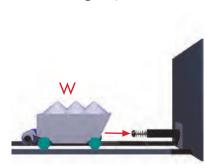
 $E_TC = E_T \times C$

 $E_TC = 10,083 \times 200$ $E_TC = 2,016,600 \text{ in-lbs./hr}$

Model OEMXT 2.0M x 2

is adequate.

EXAMPLE 7: Horizontal Moving Load, Motor Driven



STEP 1: Application Data

(W) Weight = 2,200 lbs. (V) Velocity = 60 in./sec.

(Hp) Motor horsepower = 1.5 Hp (C) Cycles/Hr = 120

STEP 2: Calculate kinetic energy

$$E_K = \frac{W}{772} \times V^2$$

 $E_{K} = \frac{2,200}{772} \times 60^{2}$

 $E_{K} = 10,259 \text{ in-lbs}$

Assume Model OEMXT 2.0M x 2 is adequate (Page 29).

STEP 3: Calculate work energy

$$F_D = \frac{19,800 \times 1.5}{60}$$

 $F_D = 495 \text{ lbs.}$

 $E_W = F_D \times S$

 $E_W = 495 \times 2$

 $E_W = 990$ in-lbs.

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W$

 $E_T = 10,259 + 990$

 $E_T = 11,249 \text{ in-lbs./c}$

STEP 5: Calculate total energy per hour

 $E_TC = E_T \times C$

 $E_TC = 11,249 \times 120$

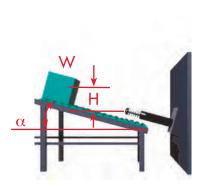
 $E_TC = 1,349,880 \text{ in-lbs./hr}$

Model OEMXT 2.0M x 2

is adequate.

EXAMPLE 8:

Free Moving Load Down an Inclined Plane



STEP 1: Application Data

(W) Weight = 550 lbs.

(H) Height = 8 in.

(α) Angle of incline = 30°

(C) Cycles/Hr = 250

STEP 2: Calculate kinetic energy

 $E_K = W \times H$

 $E_K = 550 \times 8$

 $E_K = 4,400$ in-lbs.

Assume Model OEMXT 1.5M x 3 is

adequate (Page 27).

STEP 3: Calculate work energy

 $F_D = W \times Sin \alpha$

 $F_D = 550 \text{ x}.5$

 $F_D = 275 \text{ lbs.}$

 $E_W = F_D x S$

 $E_W = 275 \times 3$

 $E_W = 825$ in-lbs.

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W$

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 $E_T = 4,400 + 825$

 $E_T = 5,225 \text{ in-lbs./c}$

STEP 5: Calculate total energy per hour

 $E_TC = E_T \times C$

 $E_TC = 5,225 \times 250$

 $E_TC = 1,306,250 \text{ in-lbs./hr}$

STEP 6: Calculate impact velocity and confirm selection

 $V = \sqrt{772 \times H}$

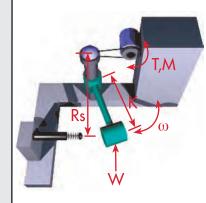
Fax: 1-716-662-0406

 $V = \sqrt{772 \times 8} = 79 \text{ in./sec.}$

Model OEMXT 1.5M x 3 is adequate.

Typical Shock Absorber Applications

Horizontal Rotating Mass



STEP 1: Application Data

(W) Weight = 200 lbs.

(ω) Angular velocity = 1.5 rad./sec.

(T) Torque = 1,065 in-lbs.

(K) Radius of gyration = 15 in.

 (R_S) Mounting radius = 20 in.

(C) Cycles/Hr = 120

STEP 2: Calculate kinetic energy

$$= \frac{W}{386} \times K^2$$

$$I = \frac{200}{386} \times 15^2$$

= 117 in-lbs./sec.²

$$\mathsf{E}_\mathsf{K} = \frac{\mathsf{I} \; \mathsf{x} \; \omega^2}{\mathbf{2}}$$

$E_{K} = \frac{117 \times 1.5^{2}}{2}$

 $E_K = 132 \text{ in-lbs.}$

Assume Model STH .5M is adequate (Page 40).

STEP 3 Calculate work energy

$$F_D = \frac{T}{R_S}$$

$$F_D = \frac{R_S}{20}$$

 $F_D = 53 \text{ lbs.}$ $E_W = F_D X S$

 $E_W = 53 \text{ X}.5$

 $E_W = 27$ in-lbs.

Overview

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W$

 $E_T = 132 + 27$

 $E_T = 159 \text{ in-lbs./c}$

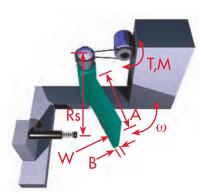
STEP 5: Calculate total energy per hour

 $E_TC = E_T X C$ $E_TC = 159 X 120$

 $E_TC = 19,080 \text{ in-lbs./hr}$

Model STH .5M is adequate.

EXAMPLE 10: Horizontal Rotating Door



STEP 1: Application Data

(W) Weight = 50 lbs.

(ω) Angular velocity = 2.5 rad./sec.

(T) Torque = 100 in-lbs.

 (R_S) Mounting radius = 20 in.

(A) Width = 40 in.

(B) Thickness = .5 in.

(C) Cycles/Hr = 250

STEP 2: Calculate kinetic energy

 $K = .289 \times \sqrt{4 \times A^2 + B^2}$

 $K = .289 \times \sqrt{4 \times 40^2 + .5^2}$

K = 23.12

 $I = \frac{W}{386} \times K^2$

$$I = \frac{50}{386} \times 23.12^2$$

 $I = 69 \text{ in-lbs./sec.}^2$

$$\mathsf{E}_\mathsf{K} = \frac{\mathsf{I} \, \mathsf{x} \, \omega^2}{\mathbf{2}}$$

$$E_K = \frac{69 \times 2.5^2}{2}$$

 $E_K = 216$ in-lbs.

Assume Model OEM .5 is adequate (Page 21).

STEP 3: Calculate work energy

$$F_D = \frac{T}{R_S}$$

$$F_D = \frac{100}{20}$$

 $F_D = 5 lbs.$

 $E_W = F_D x S = 5 x .5 = 2.5 in-lbs.$

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W = 216 + 2.5 =$ 218.5 in-lbs./c

STEP 5: Calculate total energy per hour

 $E_TC = E_T \times C = 218.5 \times 250 =$ 54,625 in-lbs./hr

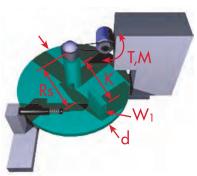
STEP 6: Calculate impact velocity and confirm selection

 $V = R_S x \omega = 20 x 2.5 = 50 in./sec.$

Model OEM .5 is adequate.

EXAMPLE 11:

Horizontal Moving Load, **Rotary Table Motor Driven with** Additional Load Installed



STEP 1: Application Data

(W) Weight = 440 lbs.

 (W_1) Installed load = 110 lbs. Rotational speed = 10 RPM

(T) Torque = 2,200 in-lbs.

Rotary table dia. = 20 in.

 (K_{Load}) Radius of gyration = 8 in. (R_S) Mounting radius = 8.86 in.

(C) Cycles/Hr = 1

(ω) Direction

Step 2: Calculate kinetic energy

$$\omega = \text{RPM x .1047} = 10 \text{ x .1047}$$

= 1.047 rad./sec.

To convert RPM to rad./sec., multiply

= **1.047** rad./sec.
I =
$$\frac{1}{386} \times K^2$$

In this case, the mass moment of inertia of the table and the mass moment of inertia of the load on the table must be calculated.

 K_{Table} =Table Radius x .707

 $K_{Table} = 10 \text{ x .707} = 7.07 \text{ in.}$ $I_{Table} = \frac{W}{386} \times K^2 \text{ Table}$

 $I_{\text{Table}} = \frac{440}{386} \times 7.07^2 = 57 \text{ in-lbs./sec.}^2$

 $I_{Load} = \frac{W_1}{386} x K^2_{Load}$

 $I_{Load} = \frac{110}{386}$ $x 8^2 = 18 \text{ in-lbs./sec.}^2$

 $E_{K} = \frac{(I_{Table} + I_{Load}) \times \omega^{2}}{}$

 $=\frac{(57+18) \times 1.047^2}{2}$ = 41 in-lbs.

Assume Model ECO 50 is adequate

STEP 3: Calculate work energy

$$F_D = \frac{I}{R_S} = \frac{2,200}{8.86} = 248 \text{ lbs.}$$

 $E_W = F_D \times S = 248 \times .875 =$ 217 in-lbs.

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W = 41 + 217 =$ 258 in-lbs./c

STEP 5: Calculate total energy per hour: not applicable, C=1

STEP 6: Calculate impact velocity and confirm selection

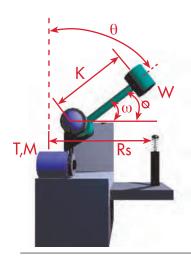
 $V = R_S \times \omega = 8.86 \times 1.047 =$ 9 in./sec.

From ECO Sizing Graph. Model ECO 50 is adequate.

Typical Shock Absorber Applications

FXΔMPIF 12·

Vertical Motor Driven Rotatina **Arm with Attached Load CASE A-Load Aided by Gravity**



STEP 1: Application Data

- (W) Weight = 110 lbs.
- (ω) Angular velocity = 2 rad./sec.
- (T) Torque = 3.100 in-lbs.
- (θ) Starting point of load from true vertical = 20°
- (Ø) Angle of rotation at impact = 30° (K_{Load}) Radius of gyration = 24 in.
- (R_S) Mounting radius = 16 in.
- (C) Cycles/Hr = 1

STEP 2: Calculate kinetic energy

$$= \frac{W}{386} \times K^2 = \frac{110}{386} \times 24^2$$

 $I = 164 \text{ in-lbs-sec}^2$

$$E_{K} = \frac{1 \times \omega^{2}}{2}$$

$$E_{K} = \frac{164 \times 2^{2}}{2}$$

 $E_K = 328$ in-lbs.

Assume Model OEM 1.0 is adequate (Page 21).

CASE A

STEP 3: Calculate work energy

$$\begin{split} F_D &= \frac{[T + (W \text{ x K x Sin } (\theta + \emptyset))]}{R_S} \\ F_D &= \frac{[3{,}100 + (110 \text{ x } 24 \text{ x } .77)]}{16} \end{split}$$

 $F_D = 320.8$ lbs.

 $E_W = F_D x S = 320.8 x 1 = 320.8 in-lbs.$

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W = 328 + 320.8$

 $E_T = 648.8 \text{ in-lbs./c}$

Overview

STEP 5: Calculate total energy per hour: not applicable, C=1

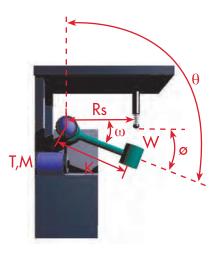
STEP 6: Calculate impact velocity and confirm selection

 $V = R_S x \omega = 16 x 2 = 32 in./sec.$

Model LROEM 1.0 is adequate. Needed for higher calculated propelling force.

EXAMPLE 13:

Vertical Motor Driven Rotating Arm with Attached Load CASE B-Load Opposing Gravity



STEP 1: Application Data

- (W) Weight = 110 lbs.
- (ω) Angular velocity = 2 rad./sec.
- (T) Torque = 3,100 in-lbs.
- (θ) Starting point of load from true vertical = 30°
- (Ø) Angle of rotation at impact = 150° (K_{Load}) Radius of gyration = 24 in.
- (R_S) Mounting radius = 16 in.
- (C) Cycles/Hr = 1

STEP 2: Calculate kinetic energy

$$I = \frac{W}{386} \times K^2 = \frac{110}{386} \times 24^2$$

 $I = 164 \text{ in-lbs-sec}^2$

$$E_{K} = \frac{1 \times \omega^{2}}{2}$$

$$E_{K} = \frac{164 \times 2^{2}}{2}$$

 $E_K = 328$ in-lbs.

Assume Model OEM 1.0 is adequate (Page 21).

CASE B

STEP 3: Calculate work energy

$$\begin{split} F_D &= \frac{[T - (W \times K \times Sin \; (\theta - \varnothing))]}{R_S} \\ F_D &= \frac{[3,100 - (110 \times 24 \times .77)]}{16} \end{split}$$

 $E_W = F_D \times S = 67 \times 1 = 67 \text{ in-lbs.}$

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W = 328 + 67$ $E_T = 394.7 \text{ in-lbs./c}$

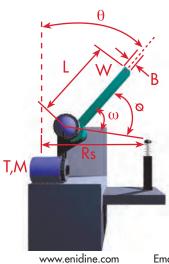
STEP 5: Calculate total energy per hour: not applicable, C=1

STEP 6: Calculate impact velocityand confirm selection.

 $V = R_S \times \omega = 16 \times 2 = 32 \text{ in./sec.}$

Model OEM 1.0 is adequate.

EXAMPLE 14: Vertical Rotating Beam



STEP 1: Application Data

- (W) Weight = 540 lbs.
- (ω) Angular velocity = 3.5 rad./sec.
- (T) Torque = 250 in-lbs.
- (θ) Starting point of load from true vertical = 20°
- (Ø) Angle of rotation at impact = 50°
- (R_s) Mounting radius = 20 in.
- (B) Thickness = 2.5 in.
- (L) Length = 24 in.
- (C) Cycles/Hr = 1

STEP 2: Calculate kinetic energy

$$K = .289 \times \sqrt{4 \times L^2 + B^2}$$

$$K = .289 \times \sqrt{4 \times 24^2 + 2.5^2} = 13.89$$

$$I = \frac{W}{386} \times K^2 = \frac{540}{386} \times 13.89$$

 $I = 270 \text{ in-lbs./sec.}^2$

$$E_K = \frac{I \times \omega^2}{2} = \frac{270 \times 3.5^2}{2} = 1,653 \text{ in-lbs.}$$

Assume Model OEM 1.5M x 2 is adequate (Page 27).

STEP 3: Calculate work energy

$$F_D = \frac{T + (W \times K \times Sin (\theta + \emptyset))}{R_S}$$

$$F_D = \frac{250 + (540 \times 13.89 \times Sin (20^\circ + 50^\circ))}{20}$$

 $F_D = 365 \text{ lbs.}$

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 $E_W = F_D \times S = 365 \times 2 = 730 \text{ in-lbs.}$

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W = 1,653 + 730 =$ 2,383 in-lbs./c

STEP 5: Calculate total energy per hour: not applicable, C=1

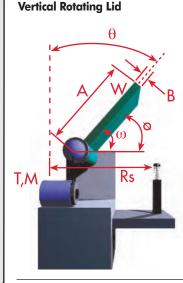
STEP 6: Calculate impact velocity and confirm selection $V = R_S x \omega = 20 x 3.5 = 70 in./sec.$

Model OEM 1.5M x 2 is adequate.

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Typical Shock Absorber Applications

EXAMPLE 15:



STEP 1: Application Data

(W) Weight = 2,000 lbs.

(ω) Angular velocity = 2 rad./sec.

(Hp) Motor horsepower = .25 Hp

 $(\boldsymbol{\theta})$ Starting point of load from

true vertical = 30°

(Ø) Angle of rotation at impact = 60°

 (R_S) Mounting radius = 30 in.

(A) Width = 60 in.

(B) Thickness = 1 in.

(C) Cycle/Hr = 1

STEP 2: Calculate kinetic energy

 $K = .289 \times \sqrt{4 \times A^2 + B^2}$

 $K = .289 \times \sqrt{4 \times 60^2 + 1^2} = 34.68 \text{ in.}$

 $I = \frac{W}{386} \times K^2 = \frac{2,000}{386} \times 34.68^2 \text{ in.}$

 $I = 6,232 \text{ in-lbs./sec.}^2$

 $E_{K} = \frac{I \times \omega^{2}}{2} = \frac{6,232 \times 2^{2}}{2}$

 $E_{K} = 12,464 \text{ in-lbs.}$

Assume Model OEM 3.0M x 2 is adequate (Page 31).

STEP 3: Calculate work energy

= **_19,800** x Hp

$$T = \frac{19,800 \times .25}{2} = 2,475 \text{ in-lbs.}$$

 $T + (W \times K \times Sin (\theta + \emptyset))$

 $F_D = \frac{2,475 + (2,000 \times 34.68 \times \sin (30^\circ + 60^\circ))}{}$

 $F_D = 2,395$ lbs.

 $E_W = F_D \times S = 2,395 \times 2 = 4,790 \text{ in-lbs.}$

Overview

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W = 12,464 + 4,790$ = 17,254 in-lbs./c

STEP 5: Calculate total energy per hour: not applicable, C=1

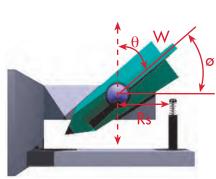
STEP 6: Calculate impact velocity and confirm selection

 $V = R_S x \omega = 30 x 2 = 60 in./sec.$

Model OEM 3.0M x 2 is adequate.

EXAMPLE 16:

Vertical Rotation with Known Intertia Aided by Gravity



STEP 1: Application Data

(W) Weight = 220.5 lbs

(I) Known Intertia = 885 in-lbs/sec.² (C/G) Center-of-Gravity = 12 in.

 (θ) Starting point from true vertical = 60°

(Ø) Angle of rotation at impact = 30° (R_S) Mounting radius = 10 in.

(C) Cycles/Hr = 1

STEP 2: Calculate kinetic energy

 $H = C/G \times [Cos(\theta) - Cos(\emptyset + \theta)]$

 $H = 12 \times [Cos(60^{\circ}) - Cos(30^{\circ}+60^{\circ})]$

 $E_K = W \times H$

 $E_{K} = 220.5 \times 6$

 $E_K = 1,323$ in-lbs.

STEP 3: Calculate work energy

 $F_D = (W \times C/G \times Sin (\theta + \emptyset))/R_S$ $F_D = (220.5 \times 12 \times Sin (60^{\circ} + 30^{\circ}))/10$

 $F_D = 264.6$ lbs.

 $E_W = F_D x S = 264.6 x 1 = 264.6 in-lbs.$

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W = 1,323 + 264.6$ $E_T = 1,587.6$ in-lbs/cyc.

STEP 5: Calculate total energy per hour: not applicable, C=1

 $E_TC = E_T \times C$

 $E_TC = 1,587.6 \times 1$

 $E_TC = 1,587.6 \text{ in-lbs/hr.}$

STEP 6: Calculate impact velocity and confirm selection

 $\omega = ((2 \times E_{K})/I) 0.5$

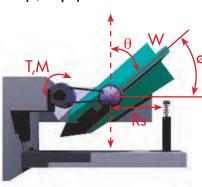
 $\omega = ((2 \text{ x 1,323})/885) \ 0.5 = 1.7$

 $V = R_S \times \omega = 10 \times 1.7 = 17 \text{ in./sec.}$

Model OEM 1.15 x 1 is adequate (Page 24).

EXAMPLE 17:

Vertical Rotation with Known Intertia Aided by Gravity (w/Torque)



STEP 1: Application Data

(W) Weight = 220.5 lbs

(ω) Angular Velocity = 2 rad/sec.

(T) Torque = 2,750 in-lbs.

(I) Known Intertia = 885 in-lbs/sec.2

(C/G) Center-of-Gravity = 12 in.

(θ) Starting point from

true vertical = 60°

(Ø) Angle of rotation at impact = 30°

 (R_S) Mounting radius = 10 in.

(C) Cycles/Hr = 100

STEP 2: Calculate kinetic energy

 $E_K = (I \times \omega^2)/2$

 $E_K = (885 \times 2^2)/2$

 $E_K = 1,770$ in-lbs.

STEP 3: Calculate work energy

 $F_D = [T - (W \times C/G \times Sin (\theta + \emptyset))]/R_S$

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 $F_D = 539.6$ lbs.

 $E_W = F_D \times S = 539.6 \times 1 = 539.6 \text{ in-lbs.}$

STEP 4: Calculate total

energy per cycle $E_T = E_K + E_W = 1,770 + 539.6$ $E_T = 2,309.6$ in-lbs/cyc.

STEP 5: Calculate total energy per hour: not applicable, C=1 $E_TC = E_T \times C$

 $E_TC = 2,309.6 \times 1$

 $E_TC = 230,960 \text{ in-lbs/hr.}$

STEP 6: Calculate impact $F_D = [2,750 - (220.5 \times 12 \times Sin (60^{\circ} + 30^{\circ})]/10$ velocity and confirm selection

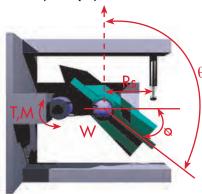
 $V = R_S x \omega = 10 x 2 = 20 in./sec.$

Model OEM 1.15 x 1 is adequate (Page 24).

Typical Shock Absorber Applications

EXAMPLE 18:

Vertical Rotation with Known Intertia Aided by Gravity (w/Torque)



STEP 1: Application Data

- (W) Weight = 220.5 lbs
- (ω) Angular Velocity = 2 rad/sec.
- (T) Torque = 2,750 in-lbs.
- (I) Known Intertia = 885 in-lbs/sec.2
- (C/G) Center-of-Gravity = 12 in.
- (θ) Starting point from true vertical = 120°
- (Ø) Angle of rotation at impact = 30° F_D = 10.4 lbs.
- (R_S) Mounting radius = 10 in.
- (C) Cycles/Hr = 100

STEP 2: Calculate kinetic energy

 $E_K = (I \times \omega^2)/2$

 $E_K = (885 \times 2^2)/2$

 $E_{K} = 1,770 \text{ in-lbs.}$

STEP 3: Calculate work energy

 $F_D = [T - (W \times C/G \times Sin (\theta - \emptyset))]/R_S$

 $F_D = [2,750 - (220.5 \text{ x} 12 \text{ x} \sin (120^{\circ} - 30^{\circ})]/10$ velocity and confirm selection

 $E_W = F_D \times S = 10.4 \times 1 = 10.4 \text{ in-lbs.}$

STEP 4: Calculate total

energy per cycle

 $E_T = E_K + E_W = 1,770 + 10.4$ $E_T = 1,780.4 \text{ in-lbs/cyc.}$

STEP 5: Calculate total energy per hour: not applicable, C=1

Overview

 $E_TC = E_T \times C$

 $E_TC = 1,780.4 \times 100$

 $E_TC = 178,040 \text{ in-lbs/hr.}$

STEP 6: Calculate impact

 $V = R_S x \omega = 10 x 2 = 20 in./sec.$

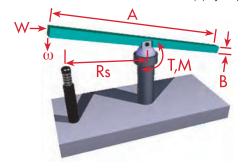
Model OEMXT 1.5M x 1 is adequate (Page 27).

EXAMPLE 19:

Vertical Roation Pinned at Center (w/Torque)

STEP 1: Application Data

- (W) Weight = 220.5 lbs.
- (ω) Angular velocity = 2 rad./sec.
- (T) Torque = 2,750 in-lbs.
- (A) Length = 40 in.
- (R_S) Mounting radius = 10 in.
- (B) Thickness = 2 in.
- (C) Cycles/Hr = 100



STEP 2: Calculate kinetic energy

 $K = .289 \times (A^2 + B^2)^{0.5}$

 $K = .289 \text{ x} (40^2 + 2^2)^{0.5} = 11.6 \text{ in.}$

 $I = (W/386) \times K^2$

 $I = (220.5/386) \times 11.6^2 = 76.9 \text{ in-lb/sec}^2$

 $E_K = (I \times \omega^2)/2$

 $E_K = (76.9 \times 2^2)/2$

 $E_{K} = 153.8$ in-lbs.

Assume Model OEM 1.0 is adequate (Page 21).

STEP 3: Calculate work energy

 $F_D = T/R_S$

 $F_D = 2,750/10$

 $F_D = 275 \text{ lbs.}$

 $E_W^- = F_D \times S = 275 \times 1 = 275 \text{ in-lbs.}$

STEP 4: Calculate total energy per cycle

 $E_T = E_K + E_W = 153.8 + 275$ $E_T = 428.8$ in-lbs./cycle

STEP 5: Calculate total energy per hour

 $E_TC = E_T \times C$

 $E_TC = 428.8 \times 100$

 $E_TC = 42,880 \text{ in-lbs./hr.}$

STEP 6: Calculate impact velocity and confirm selection

 $V = R_S \times \omega = 10 \times 2 = 20 \text{ in./sec.}$

Model OEM 1.0 is adequate.



Overview

Calculaions assume worst case scenario of 90% trolley weight over one rail.

Crane A		Per Buffer
Propelling Force Crane	lbs.	
Propelling Force Trolley	lbs.	
Weight of Crane (W _a)	lbs.	
Weight of Trolley (W _{ta})	lbs.	
Crane Velocity (Va)	in./sec.	
Trolley Velocity (V _{ta})	in./sec.	

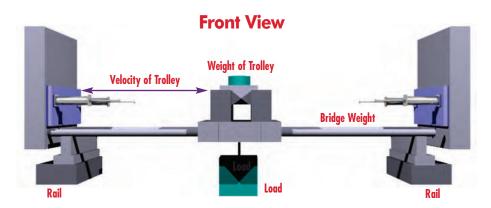
Crane B		Per Buffer
Propelling Force Crane	lbs.	
Propelling Force Trolley	lbs.	
Weight of Crane (Wb)	lbs.	
Weight of Trolley (W _{tb})	lbs.	
Crane Velocity (V _b)	in./sec.	
Trolley Velocity (V _{tb})	in./sec.	

Crane C		Per Buffer
Propelling Force Crane	lbs.	
Propelling Force Trolley	lbs.	
Weight of Crane (W _c)	lbs.	
Weight of Trolley (W _{tc})	lbs.	
Crane Velocity (V _C)	in./sec.	
Trolley Velocity (V _{tc})	in./sec.	

Please note:

Unless instructed otherwise, ITT Enidine will always calculate with:

- 100% velocity v, and
- 100% propelling force F_D



Plan Views

Application 1

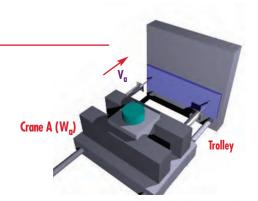
Crane A against Solid Stop Velocity:

 $V_r = V_a$

v_r - v

Impact weight per buffer:

$$W_d = \frac{Wa + (1.8) Wta}{Total Number of Shocks}$$



Application 2

Crane A against Crane B

Velocity:

$$V_r = V_{a+} V_b$$

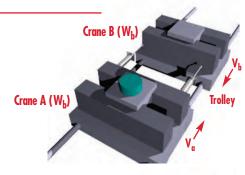
Impact weight per buffer:

$$W_1 = Wa + (1.8) Wta$$

 $W_2 = Wb + (1.8) Wtb$

$$W_1 = W_1 + (1.0) W_1 W_2$$

$$W_{d} = \frac{W_{1} W_{2}}{(W_{1} + W_{2})(Total Number of Shocks)}$$



Application 3

Crane B against Crane C

Velocity:

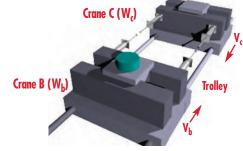
$$V_r = \frac{V_b + V_c}{2}$$

Impact weight per buffer:

$$W_1 = Wb + (1.8) Wtb$$

$$W_2 = W_C + (1.8) W_C$$

$$W_d = \frac{2 W_1 W_2}{(W_1 + W_2)(\text{Number of Shocks Per Rail})}$$



Application 4

Crane C against Solid Stop with Buffer

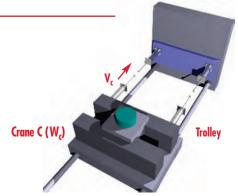
Velocity:

$$V_r = \frac{V_c}{2}$$

Impact weight per buffer:

$$W_1 = W_c + 1.8 (W_{tc})$$

$$W_d = \frac{2 W_1}{\text{Number of Shocks Per Rail}}$$



Tel.: 1-800-852-8508

Typical Shock Absorber and Crane Applications

Overview

Please note that this example is not based on any particular standard. The slung load can swing freely, and is therefore not taken into account in the calculation.

Calculation Example for Harbor Cranes as Application 1

Bridge Weight: 837,750 lbs.

Weight of Trolley: 99,200 lbs.

Crane Velocity: 60 in./sec.

Required Stroke: 24 in.

160 in./sec. **Trolley Velocity:**

Required Stroke: 40 in. **Given Values**

 $W_d = \frac{Wa + (1.8) Wta}{Total Number of Shocks}$

$$W_d = \frac{837,750 + (1.8)(99,200)}{2}$$

 $W_d = 508,155 \text{ lbs.}$

Determination of the Maximum Impact Weight W_d per Buffer

 $E_K = \frac{W_d}{772} \bullet V_r^2$

$$E_{K} = \frac{508,155 \text{ lbs.}}{772} \bullet (60 \text{ in./sec.})^{2}$$

 $E_K = 2,369,635$ in-lbs.

 $V_r = V_q$ (Application 1)

 E_{κ} = Kinetic Energy

 $\eta = Efficiency$

Determine Size of Shock Absorber for Crane

Selecting for required 24-inch stroke:

HD 5.0 x 24, maximum shock force ca. 116,159 lbs =
$$F_s = \frac{E_K}{s \bullet r}$$

W_t = Trolley Weight per Shock Absorber

$$W_t = \frac{99,200 \text{ lbs}}{2}$$

 $W_t = 49,600 \text{ lbs.}$

$$E_K = \frac{W_t}{772} \bullet V_t^2$$

$$E_K = \frac{49,600 \text{ lbs.}}{772} \bullet (160 \text{ in./sec.})^2$$

 $E_K = 1,644,767$ in-lbs.

Selecting for required 40-inch stroke:

HDN 4.0 x 40, maximum shock force ca. 48,376 lbs. = $F_s = E_K$

Determine Size of Shock Absorber for Trolley

Fax: 1-716-662-0406



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Application 1	Value
Buffer Distance H	ft.
Distance X ₁	ft.
Distance Y ₁	ft.
Distance X ₂	ft.
Distance Y ₂	ft.
Total Weight	lbs.
W _{max d}	lbs.
W _{min d}	lbs.
W _{max u}	lbs.
W _{min u}	lbs.



Calculation Example Stacker Cranes

Please note that this example shows how to calculate the maximum impact weight on the upper and lower shock absorbers for a stacker crane.

Distance Between Buffers:	H = 60 ft.	
Distance to C of G1 - Upper:	$X_1 = 45 \text{ ft.}$	
Distance to C of G1 - Lower:	Y ₁ = 15 ft.	
Distance to C of G2 - Upper:	$X_2 = 21$ ft.	Given Values
Distance to C of G1 - Lower:	Y ₂ = 39 ft.	
Total Weight:	W = 40,000 lbs.	
$W_{\text{max d}} = \frac{X_1}{H} \bullet W$	$W_{\text{max d}} = \frac{X_2}{H} \bullet W$	
$W_{\text{max d}} = \frac{15 \text{ m}}{20 \text{ m}} \bullet 20 \text{ t}$	$W_{\text{max d}} = \frac{21 \text{ ft.}}{60 \text{ ft.}} - 40,000 \text{ lbs.}$	Calculation for Lower Shock Absorbers
$W_{\text{max d}} = 15 \text{ t}$	$W_{\text{max d}} = 14,000 \text{ lbs.}$	
$W_{\text{max d}} = \frac{Y_1}{H} \bullet W$	$W_{\text{max d}} = \frac{Y_2}{H} \bullet W$	
$W_{\text{max d}} = \frac{5 \text{ m}}{20 \text{ m}} \bullet 20 \text{ t}$	$W_{\text{max d}} = \frac{39 \text{ ft.}}{60 \text{ ft.}} \bullet 40,000 \text{ lbs.}$	Calculation for Upper Shock Absorbers
$W_{\text{max d}} = 5 \text{ t}$	$W_{\text{max d}} = 26,000 \text{ lbs.}$	

calculated, and a shock absorber selected.

Using the value for W_{max} obtained above, the kinetic energy can be

Shock Absorber

Selection

Typical Applications



Overhead Crane Applications



Cargo Crane Applications



Stacker Crane Applications

ENIDINE

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Tel.: 1-800-852-8508

Typical Selections

Technical Data

Use this ITT Enidine Product Quick Selection Guide to quickly locate potential shock absorber models most suited for your requirements. Models are organized in order of smallest to largest energy capacity per cycle within their respective product families.

ITT Enidine Adjustable Shock Absorbers											
Catalog No. (Model)	(S) Stroke (in.) 1 in. = 25,4mm	(E _T) Max. inlbs./cycle 1 inlb. =		Damping Type	Page No.						
OEM 0.1M (B)	0.28	62	120,000	D	21						
ECO OEM .15M (B)	0.38	62	185,000	D	21						
ECO OEM .25 (B)	0.38	62	195,000	D	21						
ECO LROEM .25 (B)	0.38	62	195,000	D	21						
ECO OEM .35 (B)	0.50	170	331,000	D	21						
ECO LROEM .35 (B)	0.50	170	331,000	D	21						
ECO OEM .5 (B)	0.50	275	311,000	D	21						
ECO LROEM .5 (B)	0.50	275	311,000	D	21						
ECO OEM 1.0 (B)	1.00	715	681,000	(21						
ECO LROEM 1.0 (B)	1.00	715	681,000	(21						
ECO OEM 1.15 X 1	1.00	1,900	737,000	(24						
ECO LROEM 1.15 X 1	1.00	1,900	737,000	(24						
ECO OEM 1.15 X 2	2.00	3,750	963,000	(24						
ECO LROEM 1.15 X 2	2.00	3,750	963,000	(24						
ECO OEM 1.25 x 1	1.00	1,900	886,000	Č	24						
ECO LROEM 1.25 x 1	1.00	1,900	886,000	C	24						
ECO OEM 1.25 x 2	2.00	3,750	1,084,000	Ċ	24						
ECO LROEM 1.25 x 2	2.00	3,750	1,084,000	C	24						
LROEMXT 3/4 x 1	1.00	3,750	1,120,000	Ċ	27						
OEMXT ³ / ₄ x 1	1.00	3,750	1,120,000	C	27						
LROEMXT 1.5M x 1	1.00	3,750	1,120,000	Č	27						
OEMXT 1.5M x 1	1.00	3,750	1,120,000	C	27						
LROEMXT 3/4 x 2	2.00	7,500	1,475,000	C	27						
OEMXT 3/4 x 2	2.00	7,500	1,475,000	C	27						
LROEMXT 1.5M x 2	2.00	7,500	1,475,000	C	27						
OEMXT 1.5M x 2	2.00	7,500	1,475,000	C	27						
OEMXT 3/4 x 3	3.00	11,500	1,775,000	C	27						
OEMXT 1.5M x 3	3.00	11,500	1,775,000	C	27						
LROEMXT 11/8 x 1	1.00	6,000	2,000,000	C	27						
LROEMXT 11/8 x 2	2.00	20,000	2,400,000	(29						
OEMXT 11/8 x 2	2.00	20,000	2,400,000	C	29						
LROEMXT 2.0M x 2	2.00	20,000	2,400,000	C	29						
OEMXT 2.0M x 2	2.00	20,000	2,400,000	C	29						
OEM 3.0M x 2	2.00	20,000	3,290,000	C	31						
OEMXT 11/8 x 4	4.00	40,000	3,200,000	C	29						
OEMXT 2.0M x 4	4.00	40,000	3,200,000	C	29						
OEM 4.0M x 2	2.00	34,000	13,300,000	C	31						
OEM 3.0M x 3.5	3.50	35,000	5,770,000	C	31						
OEMXT 11/8 x 6	6.00	60,000	3,730,000	C	29						
OEMXT 2.0M x 6	6.00	60,000	3,730,000	C	29						
OEM 3.0M x 5	5.00	50,000	8,260,000	C	31						
OEM 3.0M x 6.5	6.50	65,000	10,750,000	C	31						
OEM 4.0M x 4	4.00	68,000	16,000,000	C	31						
OEM 4.0M x 6	6.00	102,000	18,600,000	C	31						
OEM 4.0M x 8	8.00	136,000	21,300,000	C	31						
OEM 4.0M x 10	10.00	170,000	24,000,000	C	31						

Catalog No. (Model)	(S) Stroke (in.)	(E _T) Max. inlbs./cycle		Damping Type	Page No.
	1 in. = 25,4mm	1 inlb. =	.11 Nm		
TK 6	0.25	9	31,863	D	39
TK 8	0.25	50	42,480	D	39
TK 21	0.25	20	36,000	D	40
ECO 8	0.25	35	55,000	SC	47
TK 10M	0.25	50	115,000	D	40
ECO 10	0.28	62	120,700	SC	47
ECO 15	0.41	106	275,000	SC	47
STH .25M	0.25	100	39,000	D	41
ECO 25	0.50	265	389,000	SC	47
ECOS 50	0.50	285	440,000	SC	47
ECO 50	0.88	550	523,000	SC	47
STH .5M	0.50	585	390,000	D	41
ECO 100	1.00	930	681,500	SC	47
PRO 110	1.56	1,860	743,500	P	50
ECO 120	1.00	1,640	743,000	SC	50
ECO 125	1.00	1,640	920,500	SC	50
PMXT 1525	1.00	3,250	1,120,000	SC	59
STH .75M	0.75	2,150	780,000	D	41
ECO 220	2.00	3,100	911,600	SC	50
ECO 225	2.00	3,100	1,124,000	SC	50
PMXT 1550	2.00	6,500	1,475,000	SC	59
STH 1.0M	1.00	4,400	1,300,000	D	41
PMXT 1575	3.00	10,000	1,775,000	SC	59
STH 1.0M x 2	2.00	8,800	2,100,000	D	41
PMXT 2050	2.00	16,500	2,400,000	SC	59
STH 1.5M x 1	1.00	10,200	2,200,000	D	41
PMXT 2100	4.00	33,000	3,200,000	SC	59
STH 1.5M x 2	2.00	20,400	3,200,000	D	41
PMXT 2150	6.00	50,000	3,730,000	SC	59

Key for Damping Type: D — Dashpot C — Conventional

P — Progressive SC — Self-compensating

Key for Damping Type: D — Dashpot C — Conventional

P — Progressive SC — Self-compensating

HDN Heavy Duty Shock Absorbers HDA

HDN, HDA Series

Overview

ITT Enidine Heavy Duty Series large-bore hydraulic shock absorbers protect equipment from large impacts in applications such as automated storage and retrieval systems, as well as overhead bridge and trolley cranes. They are available in a wide variety of stroke lengths and damping characteristics to increase equipment life and meet stringent deceleration requirements.

HDN Series

Custom-orificed design accommodates specified damping requirements. Computer generated output performance simulation is used to optimize the orifice configuration. Available in standard bore dimensions of up to 4 in. (100mm) and strokes over 60 in. (1524mm).

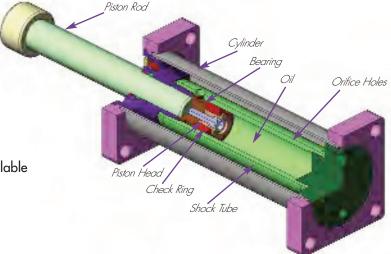
HDA Series

Adjustable units enable the user to modify shock absorber resistance to accommodate load velocity variations, with strokes up to 12in. (305mm). Standard adjustable configurations available.



Features and Benefits HDN, HDA

- Designed with Environmentally friendly materials and fluids
- Compact design smoothly and safely decelerates large energy capacity loads up to 3,000,000 in-lbs. per cycle (330 000 Nm)
- Internal charged air/oil accumulator replaces mechanical return springs, providing shorter overall length and reduced weight. **Optional** Bladder Accumulator (BA) for higher cycle rates also available.
- Engineered to meet OSHA, AISE, CMAA and other safety specifications such as DIN and FEM.
- Wide variety of optional configurations including bellows, clevis mounts and safety cables.
- Zinc plated external components provide excellent corrosion protection.
- Epoxy painting and special rod materials are available for use in highly corrosive environments.
- All sizes are fully field repairable.
- Piston rod extension sensor systems available for re-use safety requirements.
- Incorporating optional fluids and seal packages can expand standard operating temperature range from 15°F to 140°F (-10°C to 60°C) to -30°F to 210°F (-35°C to 100°C)



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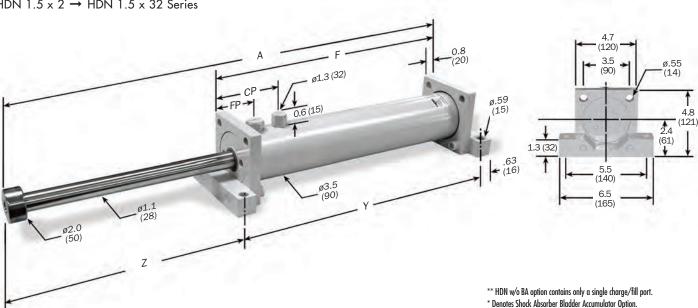
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Technical Data

Note: For TF, FF and FR mounting, delete front foot and dimensions.

Dimensions are in inches (millimeters).

HDN 1.5 x 2 → HDN 1.5 x 32 Series



				(F _P)	Nominal	Nominal					With	ВА	CP**	Model
Catalog No./ Model	(S) Stroke in. (mm)	(E _T) Max. inlbs./cycle (Nm/cycle)	(E _T C) Max. inlbs./hour (Nm/hr)	Max. Shock Force lbs. (N)	Return Force BA* lbs. (N)	Return Force w/o BA* lbs. (N)	A in. (mm)	F in. (mm)	Y in. (mm)	Z in. (mm)	CP BA* in. (mm)	FP BA* in. (mm)	w/o BA* in. (mm)	Weight lbs. (Kg)
HDN 1.5 x 2	2	27,900	1,676,000	15,750	50	70	12.2	8.2	9.4	3.4	5.5	3.4	1.6	22
	(50)	(3 200)	(189 000)	(70 060)	(220)	(320)	(310)	(208)	(240)	(86)	(139)	(86)	(41)	(10)
HDN 1.5 x 4	4 (100)	54,200 (6 100)	3,257,300 (368 000)	15,750 (70 060)	50 (220)	90 (410)	16.1 (410)	10.2 (258)	11.4 (290)	5.4 (136)	5.5 (139)	3.4 (86)	1.6	24 (12)
HDN 1.5 x 6	6	80,600	4,838,500	15,750	50	100	20.1	12.1	13.4	7.3	5.5	3.4	1.6	26
	(150)	(9 100)	(546 700)	(70 060)	(220)	(450)	(510)	(308)	(340)	(186)	(139)	(86)	(41)	(12)
HDN 1.5 x 8	8	108,000	6,482,900	15,750	50	120	24.1	14.2	15.4	9.3	5.5	3.4	1.6	29
	(200)	(12 200)	(732 500)	(70 060)	(220)	(525)	(613)	(360)	(392)	(237)	(139)	(86)	(41)	(13)
HDN 1.5 x 10	10	134,900	6,912,000	15,750	50	135	28.2	16.2	17.4	11.3	5.5	3.4	1.6	31
	(250)	(15 200)	(781 000)	(70 060)	(220)	(600)	(715)	(411)	(443)	(288)	(139)	(86)	(41)	(14)
HDN 1.5 x 12	12	161,800	7,769,700	15,750	50	210	32.2	18.2	19.4	13.3	5.5	3.4	1.6	35
	(300)	(18 300)	(877,900)	(70 060)	(220)	(920)	(817)	(462)	(494)	(339)	(139)	(86)	(41)	(16)
HDN 1.5 x 14	14	185,100	8,610,500	15,750	50	250	36.1	20.2	21.4	15.4	5.5	3.4	1.6	37
	(350)	(20 900)	(972,900)	(70 060)	(220)	(1 120)	(918)	(512)	(544)	(390)	(139)	(86)	(41)	(17)
HDN 1.5 x 16	16	208,300	9,468,200	13,500	50	250	40.1	22.2	23.4	17.3	5.5	3.4	1.6	40
	(400)	(23 300)	(1 069 800)	(60 060)	(220)	(1 120)	(1 019)	(563)	(595)	(440)	(139)	(86)	(41)	(18)
HDN 1.5 x 18	18	224,300	10,325,900	10,750	50	250	44.1	24.2	25.4	19.3	5.5	3.4	1.6	42
	(450)	(25 300)	(1 166 700)	(47 820)	(220)	(1 120)	(1 121)	(614)	(646)	(491)	(139)	(86)	(41)	(19)
HDN 1.5 x 20	20	240,300	11,183,600	8,750	50	250	48.2	26.2	27.4	21.4	5.5	3.4	1.6	44
	(500)	(27 200)	(1 263 600)	(38 920)	(220)	(1 120)	(1 223)	(665)	(697)	(542)	(139)	(86)	(41)	(20)
HDN 1.5 x 24	24	269,600	12,899,000	6,250	50	250	56.2	30.2	31.5	21.3	5.5	3.4	1.6	50
	(600)	(30 500)	(1 457 400)	(27 800)	(220)	(1 120)	(1 427)	(767)	(799)	(644)	(139)	(86)	(41)	(23)
HDN 1.5 x 28	28	297,000	14,597,600	4,750	50	250	64.1	34.2	35.4	29.3	5.5	3.4	1.6	56
	(713)	(33 600)	(1 649 300)	(21,130)	(220)	(1 120)	(1 629)	(868)	(900)	(745)	(139)	(86)	(41)	(25)
HDN 1.5 x 32	32	322,800	16,279,300	3,700	50	250	72.0	38.1	39.4	33.3	5.5	3.4	1.6	62
	(813)	(36 500)	(1 839 300)	(16 460)	(220)	(1 120)	(1 830)	(968)	(1 000)	(846)	(139)	(86)	(41)	(28)

Notes: 1. HDN shock absorbers will function satisfactorily at 5% of their maximum rated energy per cycle. If less than these values, a smaller model should be specified.

Email: industrialsales@enidine.com

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^{2.} It is recommended that the customer consult ITT Enidine for safety-related overhead crane applications.

^{3.} The energy data listed is for ideal linear impacts only. If side load conditions exist in the application, contact ITT Enidine for sizing assistance.

^{4.} Rear flange mounting of 12 inch (300 mm) strokes and longer not recommended. Front and rear flange or foot mount configurations are recommended.

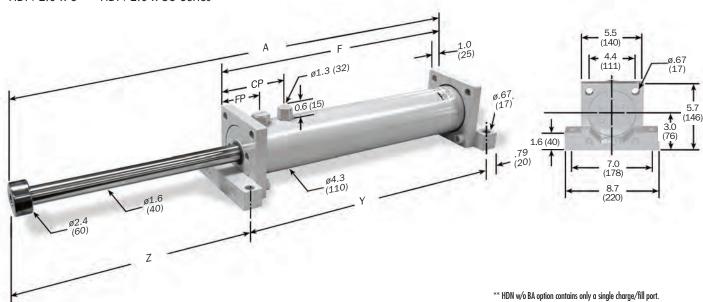
^{5.} Maximum cycle rate is 60 cycles/hr. for HDN with BA (Bladder Accumulator) option and 30 cycles/hr. without BA option.

^{6.} For impact velocities over 180 in./sec. (4.5 m/s), consult factory.

Heavy Duty Series Shock Absorber

HDN 2.0 Series

Technical Data HDN 2.0 x 6 → HDN 2.0 x 56 Series



Dimensions are in inches (millimeters).

* Denotes Shock Absorber Bladder Accumulator Option. Note: For TF, FF and FR mounting, delete front foot and dimensions.

				(F _P)	Nominal	Nominal					With	ВА	CP**	Model
Catalog No./ Model	(S) Stroke in. (mm)	(E _T) Max. inlbs./cycle (Nm/cycle)	(E _T C) Max. inlbs./hour (Nm/hr)	Max. Shock Force lbs. (N)	Return Force BA* lbs. (N)	Return Force w/o BA* lbs. (N)	A in. (mm)	F in. (mm)	Y in. (mm)	Z in. (mm)	CP BA* in. (mm)	FP BA* in. (mm)	w/o BA* in. (mm)	Weight lbs. (Kg)
HDN 2.0 x 6	6	127,200	7,629,900	25,000	120	200	21.8	13.3	14.9	7.6	6.9	3.8	1.8	42
	(152) 8	(14 400) 169,800	(862 100) 8,086,900	(111 200) 25,000	(535) 120	(870) 235	(553) 25.8	(339) 15.4	(379) 16.9	(194) 9.6	(176) 6.9	(96) 3.8	(46) 1.8	(19) 46
HDN 2.0 x 8	o (203)	(19 200)	(913 700)	(111 200)	(535)	(1 040)	(655)	(390)	(430)	9.0 (245)	(176)	3.0 (96)	(46)	(20)
	10	212,500	9,144,400	25,000	120	300	29.8	17.4	18.9	11.7	6.9	3.8	1.8	51
HDN 2.0 x 10	(250)	(24 000)	(1 033 200)	(111 200)	(535)	(1 340)	(757)	(441)	(481)	(296)	(176)	(96)	(46)	(23)
	12	253,200	10,201,900	25,000	120	515	33.8	19.4	20.9	13.7	6.9	3.8	1.8	55
HDN 2.0 x 12	(300)	(28 600)	(1 152 700)	(111 200)	(535)	(2 290)	(859)	(492)	(532)	(347)	(176)	(96)	(46)	(25)
	14	285,900	11,259,500	25,000	120	515	37.8	21.4	23.0	15.6	6.9	3.8	1.8	60
HDN 2.0 x 14	(350)	(32 300)	(1 272 100)	(111 200)	(535)	(2 290)	(960)	(543)	(583)	(397)	(176)	(96)	(46)	(27)
UDN 0.0 1/	16	318,700	12,317,000	25,000	120	515	41.8	23.4	25.0	17.6	6.9	3.8	1.8	64
HDN 2.0 x 16	(400)	(36 000)	(1 391 600)	(111 200)	(535)	(2 290)	(1 062)	(594)	(634)	(448)	(176)	(96)	(46)	(29)
HDN 2.0 x 18	18	351,500	13,374,500	25,000	120	515	45.8	25.4	27.0	19.6	6.9	3.8	1.8	68
11DN 2.0 X 10	(450)	(39 700)	(1 511 100)	(111 200)	(535)	(2 290)	(1 164)	(645)	(685)	(499)	(176)	(96)	(46)	(31)
HDN 2.0 x 20	20	383,600	14,411,300	25,000	120	515	49.8	27.4	28.9	21.7	6.9	3.8	1.8	73
11511 2.0 X 20	(500)	(43 300)	(1 628 300)	(111 200)	(535)	(2 290)	(1 265)	(695)	(735)	(550)	(176)	(96)	(46)	(33)
HDN 2.0 x 24	24	449,100	16,526,300	25,000	120	515	57.8	31.4	33.0	25.7	6.9	3.8	1.8	79
	(600)	(50 700)	(1 867 200)	(111 200)	(535)	(2 290)	(1 469)	(797)	(837)	(652)	(176)	(96)	(46)	(36)
HDN 2.0 x 28	28	514,678	18,641,400	25,000	120	515	65.8	35.4	37.0	29.6	6.9	3.8	1.8	93
	(700)	(58 200)	(2 106 200)	(111 200)	(535)	(2 290)	(1 672)	(899)	(939)	(753)	(176)	(96)	(46)	(42)
HDN 2.0 x 32	32	625,600	22,373,800	25,000	120	515	76.9	42.5	44.1	33.6	10.1	6.9	1.8	108
11511 210 X 02	(800)	(70 700)	(2 527 900)	(111 200)	(535)	(2 290)	(1 953)	(1 079)	(1 119)	(854)	(256)	(176)	(46)	(49)
HDN 2.0 x 36	36	689,500	24,447,300	22,500	120	515	84.7	46.4	48.0	37.5	10.1	6.9	1.8	117
11511 2.0 X 00	(900)	(77 900)	(2 762 200)	(100 000)	(535)	(2 290)	(2 151)	(1 179)	(1 219)	(952)	(256)	(176)	(46)	(53)
HDN 2.0 x 40	40	746,700	26,520,900	19,000	120	515	92.6	50.4	51.9	41.4	10.1	6.9	1.8	124
11DA 2.0 A 40	(1 000)	(84,400)	(2 996 500)	(84 500)	(535)	(2 290)	(2 351)	(1 279)		(1 052)	(256)	(176)	(46)	(56)
HDN 2.0 x 48	48	844,100	30,668,000	13,500	120	515	108.3	58.2	59.8	49.3	10.1	6.9	1.8	141
11DA 2.0 X 40	(1 200)	(95 400)	(3 465 000)	(60 000)	(535)	(2 290)	(2 751)	(1 479)	(1 519)	(1 252)	(256)	(176)	(46)	(64)
HDN 2.0 x 56	56	922,300	35,022,500	7,900	120	515	124.8	66.5	68.1	57.6	10.1/38.4**	6.9	1.8	161
11DN 2.0 X 30	(1 400)	(104 200)	(3 957 000)	(35 100)	(535)	(2 290)	(3 171)	(1 689)	(1 729)	(1 462)	(256)/(975)	(176)	(46)	(73)

Notes: 1. HDN shock absorbers will function satisfactorily at 5% of their maximum rated energy per cycle. If less than these values, a smaller model should be specified.

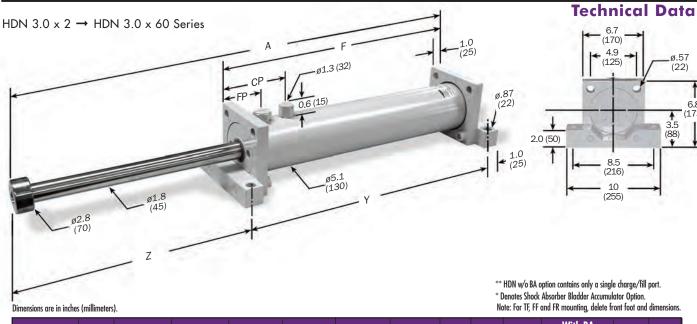
- 2. It is recommended that the customer consult ITT Enidine for safety-related overhead crane applications.
- 3. The energy data listed is for ideal linear impacts only. If side load conditions exist in the application, contact ITT Enidine for sizing assistance.
- 4. Rear flange mounting of 12 inch (300 mm) strokes and longer not recommended. Front and rear flange or foot mount configurations are recommended.
- 5. Maximum cycle rate is 60 cycles/hr. for HDN with BA (Bladder Accumulator) option and 30 cycles/hr. without BA option.
- 6. For impact velocities over 180 in./sec. (4.5 m/s), consult factory.
- 7. ** HDN 2.0 \times 56 has two charge ports.



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Heavy Duty Series Shock Absorber

HDN 3.0 Series



				(F _P)	Nominal	Nominal					With	With BA		Model
Catalog No./ Model	(S) Stroke in. (mm)	(E _T) Max. inlbs./cycle (Nm/cycle)	(Nm/hr)	Max. Inital Shock Force Ibs. (N)	Return Force BA* Ibs. (N)	Return Force w/o BA* lbs. (N)	A in. (mm)	F in. (mm)	Y in. (mm)	Z in. (mm)	CP BA* in. (mm)	FP BA* in. (mm)	w/o BA* in. (mm)	Weight Ibs. (Kg)
HDN 3.0 x 2	2	85,300	5,120,100	50,000	150	255	13.2	8.0	10.0	4.3	5.0	2.4	1.8	40
	(50)	(9 600)	(578 500)	(222 400)	(670) 160	(1 130) 405	(336)	(203) 9.0	(253) 11.0	(108) 5.2	(128) 5.0	(61) 2.4	(46) 1.8	(21)
HDN 3.0 x 3	3 (75)	128,800 (14 600)	5,832,300 (659 000)	50,000 (222 400)	(710)	(1 810)	15.2 (387)	(229)	(279)	(133)	(128)	2.4 (61)	(46)	42 (22)
	5	214,200	7,131,200	50,000	165	650	19.3	11.0	13.0	7.2	5.0	2.4	1.8	48
HDN 3.0 x 5	(125)	(24 200)	(805 700)	(222 400)	(735)	(2 895)	(489)	(280)	(330)	(184)	(128)	(61)	(46)	(25)
UDM 2.0 0	8	316,100	9,041,400	50,000	170	650	25.2	14.0	15.9	10.2	5.0	2.4	1.8	57
HDN 3.0 x 8	(200)	(35 700)	(1 021 500)	(222 400)	(755)	(2 895)	(640)	(355)	(405)	(260)	(128)	(61)	(46)	(29)
HDN 3.0 x 10	10	382,600	10,340,300	50,000	175	650	29.2	16.0	18.0	12.2	5.0	2.4	1.8	64
10N 3.0 X 10	(250)	(43 200)	(1 168 300)	(222 400)	(780)	(2 895)	(742)	(406)	(456)	(311)	(128)	(61)	(46)	(32)
HDN 3.0 x 12	12	449,100	11,639,200	50,000	175	650	33.2	18.0	20.0	14.3	5.0	2.4	1.8	71
11DIT 0.0 X 12	(300)	(50 700)	(1 315 000)	(222 400)	(780)	(2 895)	(844)	(457)	(507)	(362)	(128)	(61)	(46)	(35)
HDN 3.0 x 14	14	556,500	14,211,500	50,000	180	650	39.2	22.0	23.9	16.2	7.0	4.4	1.8	88
	(350) 16	(62 900) 623,000	(1 605 700) 15,510,400	(222 400) 50,000	(800) 180	(2 895) 650	(995) 43.2	(558)	(608) 25.9	(412) 18.2	(178) 7.0	(111)	(46) 1.8	(43) 93
HDN 3.0 x 16	(400)	(70 400)	(1 752 400)	(222 400)	(800)	(2 895)	(1 097)	(609)	(659)	(463)	(178)	(111)	(46)	(45)
	18	689,400	16,809,300	50,000	180	650	47.2	26.0	28.0	20.2	7.0	4.4	1.8	99
HDN 3.0 x 18	(450)	(77 900)	(1 899 200)	(222 400)	(800)	(2 895)	(1 199)	(660)	(710)	(514)	(178)	(111)	(46)	(48)
	20	755,900	18,108,200	50,000	180	650	51.2	28.0	30.0	22.2	7.0	4.4	1.8	106
HDN 3.0 x 20	(500)	(85 400)	(2 046 000)	(222 400)	(800)	(2 895)	(1 301)	(711)	(761)	(565)	(178)	(111)	(46)	(51)
UDM 2.0 04	24	887,600	20,680,500	50,000	180	650	59.2	32.0	33.9	26.3	7.0	4.4	1.8	119
HDN 3.0 x 24	(600)	(100 300)	(2 336 600)	(222 400)	(800)	(2 895)	(1 504)	(812)	(862)	(667)	(178)	(111)	(46)	(57)
HDN 3.0 x 28	28	1,020,600	23,278,300	50,000	180	650	67.2	36.0	38.0	30.2	7.0	4.4	1.8	130
11DN 3.0 X 20	(700)	(115 300)	(2 630 100)	(222 400)	(800)	(2 895)	(1 707)	(914)	(964)	(768)	(178)	(111)	(46)	(62)
HDN 3.0 x 32	32	1,152,200	25,850,700	40,500	180	650	75.2	40.0	41.9	34.3	7.0	6.3	1.8	143
IIDII OIO X OZ	(800)	(130 200)	(2 920 700)	(180 200)	(800) 180	(2 895) 650	(1 910)	(1 015) 45.8	(1 065) 47.8	(870) 38.1	(178) 9.0	(161)	(46) 1.8	(68)
HDN 3.0 x 36	36 (900)	1,307,100 (147 700)	29,645,500 (3 349 500)	36,000 (160 100)	(800)	(2 895)	84.9 (2 156)	(1 164)	47.0 (1 214)	(967)	(228)	6.3 (161)	(46)	163 (77)
	40	1,412,700	32,192,300	31,500	180	650	92.8	49.8	51.7	42.0	9.0	6.3	1.8	176
HDN 3.0 x 40	(1 000)	(159 600)	(3 637 200)	(140 000)	(800)	(2 895)	(2 356)	(1 264)	(1 314)	(1 067)	(228)	(161)	(46)	(85)
	48	1,590,700	37,286,100	21,500	185	650	108.5	57.6	59.6	49.9	9.0	6.3	1.8	200
HDN 3.0 x 48	(1 200)	(179 700)	(4 212 800)	(95 600)	(825)	(2 895)	(2 756)	(1 464)	(1 514)	(1 267)	(228)	(161)	(46)	(94)
UDM 0.0	56	1,741,300	42,379,800	12,500	185	650	124.3	65.5	67.5	57.8	9.0/37.3**	6.3	1.8	235
HDN 3.0 x 56	(1 400)	(196 700)	(4 788 300)	(55 600)	(825)	(2 895)	(3 156)	(1 664)	(1 714)	(1 467)	(228)/(947)	(161)	(46)	(106)
HDN 3.0 x 60	60	1,830,400	45,283,200	11,950	185	650	133.2	70.0	72.0	62.2	9.0/39.5**	6.3	1.8	235
UNI 3.0 X 00	(1 500)	(206 800)	(5 116 300)	(53 200)	(825)	(2 895)	(3 384)	(1 778)	(1 828)	(1 581)	(228)/(1004)	(161)	(46)	(106)
HDN 3.0 x 64	64	1,921,500	46,116,000	11,950	185	650	145.2	78.0	79.9	66.3	12.9/60.1	10.2	1.8	245
11D11 0.0 X 04	(1 629)	(217 100)	(5 210 400)	(53 200)	(825)	(2 895)	(3 688)	(1 980)	(2 030)	(1 683)	(328)/(1 527)	(260)	(46)	(110)
HDN 3.0 x 72	72 (1 830)	2,106,500 (238 000)	55,245,000 (6 242 000)	11,950 (53 200)	185 (825)	650 (2 895)	158.0 (4 012)	82.5 (2 092)	84.5 (2 142)	74.6 (1 895)	17.3/68.0 (439)/(1727)	10.2 (260)	1.8 (46)	260 (118)

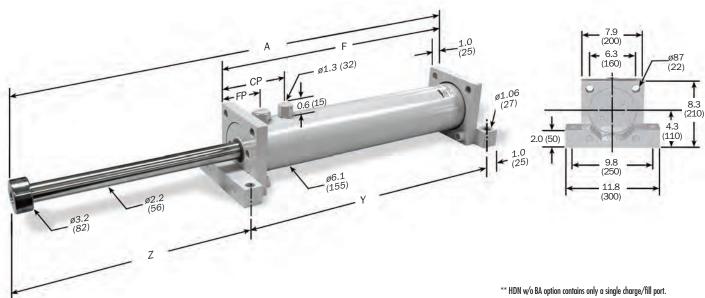
- Notes: 1. HDN shock absorbers will function satisfactorily at 5% of their maximum rated energy per cycle. If less than these values, a smaller model should be specified.

 5. Maximum cycle rate is 60 cycles/hr. for HDN with BA option and 30 cycles/hr. without BA (Bladder Accumulator) option.
 - 2. It is recommended that the customer consult ITT Enidine for safety-related overhead crane applications.
 - 3. The energy data listed is for ideal linear impacts only. If side load conditions exist in the application, contact ITT Enidine for sizing assistance.
 - 4. Rear flange mounting of 12 inch (300 mm) strokes and longer not recommended. Front and rear flange or foot mount configurations are recommended.
- 6. For impact velocities over 180 in./sec. (4.5 m/s), consult factory.
- 7. ** HDN 3.0 x 56 and HDN 3.0 x 60 have 2 charge ports.



HDN HDA **Heavy Duty Series Shock Absorber** HDN 3.5 Series

Technical Data HDN $3.5 \times 2 \rightarrow$ HDN 3.5×56 Series



Dimensions are in inches (millimeters)

* Denotes Shock Absorber Bladder Accumulator Option.

Note: For TF, FF and FR mounting, delete front foot and dimensions.

				(F _P)	Nominal	Nominal					With	BA	CP**	Model
Catalog No./ Model	(S) Stroke in. (mm)	(E _T) Max. inlbs./cycle (Nm/cycle)	(E _T C) Max. inlbs./hour (Nm/hr)	Max. Shock Force lbs. (N)	Return Force BA* lbs. (N)	Return Force w/o BA* lbs. (N)	A in. (mm)	F in. (mm)	Y in. (mm)	Z in. (mm)	CP BA* in. (mm)	FP BA* in. (mm)	w/o BA* in. (mm)	Weight Ibs. (Kg)
HDN 3.5 x 2	2	115,200	6,912,100	67,500	215	455	13.9	9.6	11.6	3.3	5.3	3.0	2.1	73
11DI 3.3 X Z	(50)	(13 000)	(781 000)	(300 250)	(960)	(2 020)	(354)	(244)	(294)	(85)	(134)	(77)	(52)	(33)
HDN 3.5 x 4	4	230,400	8,793,200	67,500	230	610	18.0	11.6	13.6	5.4	5.3	3.0	2.1	82
11DI 3.3 X 7	(100)	(26 000)	(993 500)	(300 250)	(1 020)	(2 710)	(456)	(295)	(345)	(136)	(134)	(77)	(52)	(37)
HDN 3.5 x 6	6	343,300	10,283,600	67,500	260	1,010	21.9	13.6	15.6	7.3	5.3	3.0	2.1	90
11DN 3.5 X 0	(150)	(38 800)	(1 161 900)	(300 250)	(1 160)	(4 480)	(556)	(345)	(395)	(186)	(134)	(77)	(52)	(41)
HDN 3.5 x 8	8	450,300	11,803,800	67,500	265	1,010	25.9	15.6	17.6	9.3	5.3	3.0	2.1	99
о х с.с ичп	(200)	(50 900)	(1 333 600)	(300 250)	(1 180)	(4 480)	(658)	(396)	(446)	(237)	(134)	(77)	(52)	(45)
IIDN 2 5 10	10	538,400	13,324,000	67,500	270	1,010	29.9	17.6	19.6	11.3	5.3	3.0	2.1	108
HDN 3.5 x 10	(250)	(60 800)	(1 505 400)	(300 250)	(1 200)	(4 480)	(760)	(447)	(497)	(288)	(134)	(77)	(52)	(49)
	12	626,500	14,844,100	67,500	270	1,010	33.9	19.6	21.6	13.3	5.3	3.0	2.1	117
HDN 3.5 x 12	(300)	(70 800)	(1 677 200)	(300 250)	(1 200)	(4 480)	(862)	(498)	(548)	(339)	(134)	(77)	(52)	(53)
UDM 0.5 17	16	801,000	17,854,700	67,500	275	1,010	41.9	23.6	25.6	17.3	5.3	3.0	2.1	132
HDN 3.5 x 16	(400)	(90 500)	(2 017 300)	(300 250)	(1 225)	(4 480)	(1 064)	(599)	(649)	(440)	(134)	(77)	(52)	(60)
	20	1,051,800	22,534,500	67,500	275	1,010	52.0	29.8	31.8	21.2	7.4	5.2	2.1	163
HDN 3.5 x 20	(500)	(118 800)	(2 546 100)	(300 250)	(1 225)	(4 480)	(1 323)	(756)	(806)	(542)	(189)	(132)	(52)	(74)
	24	1,228,000	25,574,800	67,500	280	1,010	60.1	33.8	35.8	25.3	7.4	5.2	2.1	179
HDN 3.5 x 24	(600)	(138 700)	(2 889 600)	(300 250)	(1 250)	(4 480)	(1 527)	(858)	(908)	(644)	(189)	(132)	(52)	(81)
	28	1,402,500	28,585,400	67,500	280	1,010	68.0	37.8	39.8	29.2	7.4	5.2	2.1	196
HDN 3.5 x 28	(700)	(158 500)	(3 229 700)	(300 250)	(1 250)	(4 480)	(1 729)	(959)	(1 009)	(745)	(189)	(132)	(52)	(89)
	32	1,578,700	31,625,800	67,500	280	1,010	76.1	41.8	43.8	33.2	7.4	5.2	2.1	214
HDN 3.5 x 32	(800)	(178 400)	(3 573 200)	(300 250)	(1 250)	(4 480)	(1 933)	(1 061)	(1 111)	(847)	(189)	(132)	(52)	(97)
	36	1,754,900	34,666,100	58,500	280	1,010	84.1	45.8	47.8	37.3	7.4	5.2	2.1	231
HDN 3.5 x 36	(900)	(198 300)	(3 916 800)	(260 200)	(1 250)	(4 480)	(2 137)	(1 163)	(1 213)	(949)	(189)	(132)	(52)	(105)
	40	1,918,600	37,676,700	48,500	280	1,010	92.1	49.8	51.8	41.3	7.4	5.2	2.1	247
HDN 3.5 x 40	(1 000)	(216 800)	(4 256 900)	(215 700)	(1 250)	(4 480)	(2 339)	(1 264)	(1 314)	(1 050)	(189)	(132)	(52)	(112)
	48	2,188,000	43,638,200	35,000	280	1,010	107.8	57.6	59.6	49.2	7.4	5.2	2.1	282
HDN 3.5 x 48	(1 200)	(247 200)	(4 930 500)	(155 700)	(1 250)	(4 480)	(2 739)	(1 464)	(1 514)	(1 250)	(189)	(132)	(52)	(128)
	56	2,418,600	49,599,700	25,300	470	1,010	123.6	65.5	67.5	57.1	7.4/48.6**	5.2	2.1	317
HDN 3.5 x 56	(1 400)	(273 300)	(5 604 000)	(112 500)	(2 100)	(4 480)	(3 139)	(1 665)			(1 894)/(1 233)	(132)	(52)	(144)

Notes: 1. HDN shock absorbers will function satisfactorily at 5% of their maximum rated energy per cycle. If less than these values, a smaller model should be specified.

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Tel.: 1-800-852-8508

^{2.} It is recommended that the customer consult ITT Enidine for safety-related overhead crane applications.

^{3.} The energy data listed is for ideal linear impacts only. If side load conditions exist in the application, contact ITT Enidine for sizing assistance.

^{4.} Rear flange mounting of 12 inch (300 mm) strokes and longer not recommended. Front and rear flange or foot mount configurations are recommended.

^{5.} Maximum cycle rate is 60 cycles/hr. for HDN with BA option and 30 cycles/hr. without BA option.

^{6.} For impact velocities over 180 in./sec. (4.5 m/s), consult factory.

^{7. **} HDN 3.5 x 56 has two charge ports.

Heavy Duty Series Shock Absorber

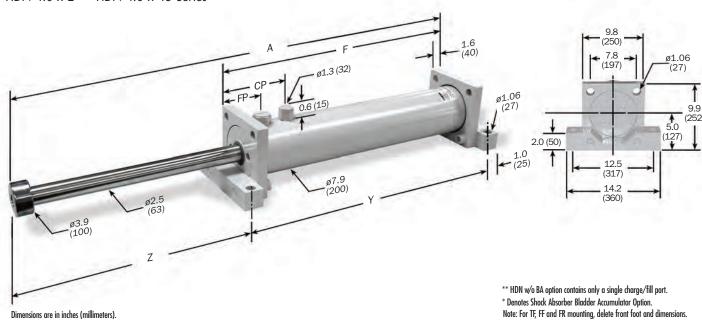
HDN 4.0 Series

HDN 4.0 x 2 → HDN 4.0 x 48 Series



With BA

CP**



Catalog No./ Model	(S) Stroke in. (mm)	(E _T) Max. inlbs./cycle (Nm/cycle)	(E _T C) Max. inlbs./hour (Nm/hr)	Max. Inital Shock Force lbs. (N)	Return Force BA* lbs. (N)	Return Force w/o BA* lbs. (N)	A in. (mm)	F in. (mm)	Y in. (mm)	Z in. (mm)	CP BA* in. (mm)	FP BA* in. (mm)	w/o BA* in. (mm)	Weight Ibs. (Kg)
HDN 4.0 x 2	2	139,200	8,352,800	80,000	250	425	16.9	11.6	13.5	4.4	8.1	4.3	2.5	141
11DN 4.0 X Z	(50)	(15 700)	(943 700)	(355 900)	(1 100)	(1 900)	(430)	(294)	(344)	(111)	(206)	(108)	(64)	(64)
HDN 4.0 x 4	4	275,700	13,579,600	80,000	270	485	20.9	13.6	15.6	6.4	8.1	4.3	2.5	154
11DN 4.0 X 4	(100)	(31 200)	(1 534 300)	(355 900)	(1 200)	(2 160)	(532)	(345)	(395)	(162)	(206)	(108)	(64)	(70)
HDN 4.0 x 6	6	409,606	15,547,700	80,000	270	690	24.9	15.6	17.5	8.3	8.1	4.3	2.5	168
11DN 4.0 X 0	(150)	(46 279)	(1 756 700)	(355 900)	(1 200)	(3 050)	(632)	(395)	(445)	(212)	(206)	(108)	(64)	(76)
HDN 4.0 x 8	8	548,800	17,594,400	80,000	270	980	28.9	17.6	19.6	10.4	8.1	4.3	2.5	181
ПИN 4.0 X O	(200)	(62 000)	(1 987 900)	(355 900)	(1 200)	(4 370)	(735)	(447)	(497)	(263)	(206)	(108)	(64)	(82)
HDN 4.0 x 10	10	682,700	19,562,500	80,000	270	1,230	32.9	19.6	21.5	12.4	8.1	4.3	2.5	192
ПDN 4.0 X 10	(250)	(77,100)	(2 210 300)	(355 900)	(1 200)	(5 465)	(836)	(497)	(547)	(314)	(206)	(108)	(64)	(87)
HDN 4.0 x 12	12	819,200	25,269,900	80,000	275	1,000	40.6	25.3	27.2	14.4	11.8	8.0	2.5	238
NUN 4.0 X 12	(300)	(92 600)	(1 855 100)	(355 900)	(1 225)	(4 440)	(1 032)	(642)	(692)	(365)	(300)	(202)	(64)	(108)
HDN 4.0 x 16	16	1,089,600	29,245,400	80,000	275	1,270	48.6	29.3	31.2	18.3	11.8	8.0	2.5	265
ПИN 4.U X 10	(400)	(123,100)	(3 304 300)	(355 900)	(1 225)	(5 650)	(1 234)	(743)	(793)	(466)	(300)	(202)	(64)	(120)
HDN 4.0 x 20	20	1,362,700	33,260,200	80,000	280	1,155	56.6	33.3	35.2	22.4	11.8	8.0	2.5	290
ПИN 4.0 X 20	(500)	(154 000)	(3 757 900)	(355 900)	(1 245)	(5 145)	(1 438)	(845)	(895)	(568)	(300)	(202)	(64)	(131)
HDN 4.0 04	24	1,635,700	37,275,000	80,000	280	1,275	64.6	37.3	39.3	26.4	11.8	8.0	2.5	317
HDN 4.0 x 24	(600)	(184 800)	(4 211 500)	(355 900)	(1 245)	(5 675)	(1 642)	(947)	(997)	(670)	(300)	(202)	(64)	(144)
UDN 4 0 20	28	1,904,200	41,250,500	80,000	280	1,275	72.6	41.3	43.2	30.4	11.8	8.0	2.5	346
HDN 4.0 x 28	(700)	(215 100)	(4 660 700)	(355 900)	(1 245)	(5 675)	(1 844)	(1 048)	(1 098)	(771)	(300)	(202)	(64)	(157)
UDM 4.0 20	32	2,128,700	45,265,400	80,000	280	1,275	80.6	45.3	47.2	34.4	11.8	8.0	2.5	375
HDN 4.0 x 32	(800)	(240 500)	(5 114 300)	(355 900)	(1 245)	(5 675)	(2 048)	(1 150)	(1 200)	(873)	(300)	(202)	(64)	(170)
IIDN 4.0 0/	36	2,353,200	49,280,200	80,000	280	1,275	88.7	49.3	51.3	38.4	11.8	8.0	2.5	403
HDN 4.0 x 36	(900)	(265 900)	(5 567 900)	(355 900)	(1 245)	(5 675)	(2 252)	(1 252)	(1 302)	(975)	(300)	(202)	(64)	(183)
HDN 4.0 × 40	40	2,566,000	53,255,700	80,000	280	1,275	96.6	53.3	55.2	42.4	11.8	8.0	2.5	430
DDN 4.U X 40														

(2 454)

112.4

(2854)

Tel.: 1-800-852-8508

(1 353)

61.3

(1 403)

63.2

(1 556) (1 606)

(1 076)

50.1

(1273)

Fax: 1-716-662-0406

(300)

11.8

(300)

(202)

8.0

(202)

(64)

2.5

(64)

(195)

485

(220)

Notes: 1. HDN shock absorbers will function satisfactorily at 5% of their maximum rated energy per cycle. If less than these values, a smaller model should be specified.

(355 900)

45,000

(200 000)

(1 245)

280

(1 245)

(5 675)

1,275

(5675)

 (F_P)

2. It is recommended that the customer consult ITT Enidine for safety-related overhead crane applications.

(6 017 100)

61,246,000

(6 919 900)

- 3. The energy data listed is for ideal linear impacts only. If side load conditions exist in the application, contact ITT Enidine for sizing assistance.
- 4. Rear flange mounting of 12 inch (300 mm) strokes and longer not recommended. Front and rear flange or foot mount configurations are recommended.
- 5. Maximum cycle rate is 60 cycles/hr. for HDN with BA option and 30 cycles/hr. without BA option.
- 6. For impact velocities over 180 in./sec. (4.5 m/s), consult factory.

(289 900)

2,914,200

(329 300)

(1000)

(1 200)

HDN 4.0 x 40

HDN 4.0 x 48

ENIDINE

HDN

Heavy Duty Adjustable Series Shock Absorber

HDA 3.0 Series

Technical Data

Dimensions are in inches (millimeters).

Note: For TF, FF and FR mounting, delete front foot and dimensions.

				(F _P)	Nominal					Witl	ı BA	Model
Catalog No./ Model	(S) Stroke in. (mm)	(E _T) Max. inlbs./cycle (Nm/cycle)	(E _T C) Max. inlbs./hour (Nm/hr)	Max. End Shock Force lbs. (N)	Return Force BA* lbs. (N)	A in. (mm)	F in. (mm)	Y in. (mm)	Z in. (mm)	CP* in. (mm)	FP* in. (mm)	Weight Ibs. (Kg)
HDA 3.0 x 2	2	40,000	2,400,000	50,000	150	13.2	8.4	10.4	3.9	4.4	2.4	40
11DA 0.0 X 2	(50)	(4 500)	(271 200)	(222 400)	(660)	(336)	(213)	(263)	(98)	(112)	(61)	(21)
HDA 3.0 x 3	3	60,000	3,600,000	50,000	160	15.2	9.4	11.4	4.8	4.4	2.4	42
пра 3.0 х 3	(75)	(6 800)	(406 700)	(222 400)	(710)	(387)	(239)	(289)	(123)	(112)	(61)	(22)
HDA 3.0 x 5	5	100,000	6,000,000	50,000	165	19.3	11.4	13.4	6.9	4.4	2.4	48
11DA 3.0 X 3	(125)	(11 300)	(677 900)	(222 400)	(730)	(489)	(290)	(340)	(174)	(112)	(61)	(25)
HDA 3.0 x 8	8	160,000	9,296,000	50,000	170	25.2	14.4	16.3	9.8	4.4	2.4	57
пра 3.0 х о	(200)	(18 100)	(1 050 300)	(222 400)	(765)	(640)	(365)	(415)	(250)	(112)	(61)	(29)
UDA 0.0 10	10	200,000	10,594,500	50,000	175	29.2	16.4	18.3	11.9	4.4	2.4	64
HDA 3.0 x 10	(250)	(22 600)	(1 197 100)	(222 400)	(775)	(742)	(416)	(466)	(301)	(112)	(61)	(32)
UDA 2.0 10	12	240,000	11,893,800	50,000	175	33.2	18.4	20.4	13.8	4.4	2.4	71
HDA 3.0 x 12	(300)	(27 200)	(1 343 800)	(222 400)	(775)	(844)	(467)	(517)	(352)	(112)	(61)	(35)

Notes: 1. HDA shock absorbers will function satisfactorily at 5% of their maximum rated energy per cycle. If less than these values, a smaller model should be specified.

- 2. It is recommended that the customer consult ITT Enidine for safety-related overhead crane applications.
- 3. The energy data listed is for ideal linear impacts only. If side load conditions exist in the application, contact ITT Enidine for sizing assistance.
- 4. Rear flange mounting of 12 inch (300 mm) strokes and longer not recommended. Front and rear flange or foot mount configurations are recommended.
- 5. Maximum cycle rate is 60 cycles/hr.
- 6. HDA models which have an impact velocity below 30 in./sec. (.8 m/sec.), please contact ITT Enidine for assistance.
- 7. Maximum allowable applied propelling force: 25,000 lbs. (111 200 N)

Adjustment Techniques

Useable Adjustment Setting Range 150 3,5 140 130 120 3,0 110 100 2,5 90 All HDA's 80 2,0 70 60 1,5 50 40 1,0 30 20 0,5 10 0 -0 **Adjustment Setting**

After properly sizing an HDA shock absorber, the useable range of adjustment settings can be determined:

- 1. Locate the intersection point of the application's impact velocity and the HDA model graph line.
- The intersection is the maximum adjustment setting to be used. Adjustments exceeding this setting could overload the shock absorber.
- 3. The useable adjustment setting range is from setting 1 to the MAXIMUM adjustment setting as determined in step 2.

EXAMPLE: HDA Series

Impact Velocity: 80 in./sec. (2 m/s)
 Intersection Point: Adjustment Setting 3

3. Useable Adjustment Setting Range: 1 to 3

ENIDINE

www.enidine.com

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Tel.: 1-800-852-8508 Fax: 1-716-662-0406

Heavy Duty Series

Heavy Duty Adjustable Series Shock Absorber

Dimensions are in inches (millimeters).

Note: For TF, FF and FR mounting, delete front foot and dimensions.

				(F _P)	Nominal					Witl	ı BA	Model
Catalog No./ Model	(S) Stroke in. (mm)	(E _T) Max. inlbs./cycle (Nm/cycle)	(E _T C) Max. inlbs./hour (Nm/hr)	Max. End Shock Force lbs. (N)	Return Force BA* lbs. (N)	A in. (mm)	F in. (mm)	Y in. (mm)	Z in. (mm)	CP* in. (mm)	FP* in. (mm)	Weight lbs. (Kg)
HDA 4.0 x 2	2	120,000	7,200,000	80,000	250	16.9	12.0	13.9	4.0	7.1	4.3	141
HDA 4.0 X Z	(50)	(13 600)	(813 500)	(355 900)	(1 125)	(430)	(304)	(354)	(101)	(180)	(108)	(64)
1104 4 0 4	4	240,000	13,973,200	80,000	250	20.9	14.0	15.9	6.0	7.1	4.3	154
HDA 4.0 x 4	(100)	(27 100)	(1 578 800)	(355 900)	(1 125)	(532)	(355)	(405)	(152)	(180)	(108)	(70)
UDA 4.0 6	6	360,000	15,941,300	80,000	250	24.9	15.9	17.9	8.0	7.1	4.3	168
HDA 4.0 x 6	(150)	(40 700)	(1 801 100)	(355 900)	(1 125)	(632)	(405)	(455)	(202)	(180)	(108)	(76)
1104.40.0	8	480,000	17,988,100	80,000	250	28.9	18.0	20.0	10.0	7.1	4.3	181
HDA 4.0 x 8	(200)	(54 200)	(2 032 400)	(355 900)	(1 125)	(735)	(457)	(507)	(253)	(180)	(108)	(82)
UDA 4.0 × 10	10	600,000	19,956,100	80,000	250	32.9	20.0	21.9	12.0	7.1	4.3	192
HDA 4.0 x 10	(250)	(67 800)	(2 254 700)	(355 900)	(1 125)	(836)	(507)	(557)	(304)	(180)	(108)	(87)

Notes: 1. HDA shock absorbers will function satisfactorily at 5% of their maximum rated energy per cycle. If less than these values, a smaller model should be specified.

- $2. \ It is recommended that the customer consult \ \dot{III} \ Enidine for safety-related overhead crane applications.$
- 3. The energy data listed is for ideal linear impacts only. If side load conditions exist in the application, contact ITT Enidine for sizing assistance.
- 4. Rear flange mounting of 12 inch (300 mm) strokes and longer not recommended. Front and rear flange or foot mount configurations are recommended.
- 5. Maximum cycle rate is 60 cycles/hr.

www.enidine.com

- 6. HDA models which have an impact velocity below 30 in./sec. (.8 m/sec.), please contact ITT Enidine for assistance.
- 7. Maximum allowable applied propelling force: 40,000 (177 900 N)

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Email: industrialsales@enidine.com Tel.: 1-800-852-8508 Fax: 1-716-662-0406 HDN

HDA

Heavy Duty Series Shock Absorber

HD Series

Overview

HD Series

Custom-orificed design accommodates specified damping requirements. Computer generated output performance simulation is used to optimize the orifice configuration. Available in standard bore dimensions of up to 5 in. (125mm) and 6 in. (156mm) with strokes over 60 in. (1525mm).



Features and Benefits HD

 Compact design smoothly and safely decelerates large energy capacity loads up to 8,000,000 in-lbs. per cycle (900 000 Nm)

 Engineered to meet OSHA, AISE, CMAA and other safety specifications such as DIN and FEM.

 Internal air charged bladder accumulator replaces mechanical return springs, providing shorter overall length and reduced weight.

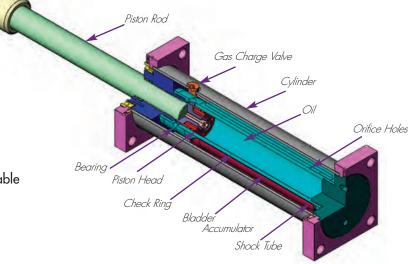
 Wide variety of optional configurations including bellows, clevis mounts and safety cables.

 Available in standard adjustable or custom-orificed non-adjustable models.

Zinc plated external components provide enhanced corrosion protection.

 Epoxy painting and special rod materials are available for use in highly corrosive environments.

- All sizes are fully field repairable.
- Piston rod extension sensor systems available for reuse safety requirements.
- Incorporating optional fluids and seal packages can expand standard operating temperature range from 15°F to 140°F to -30°F to 210°F (-10°C to 60°C) to (-35°C to 100°C)



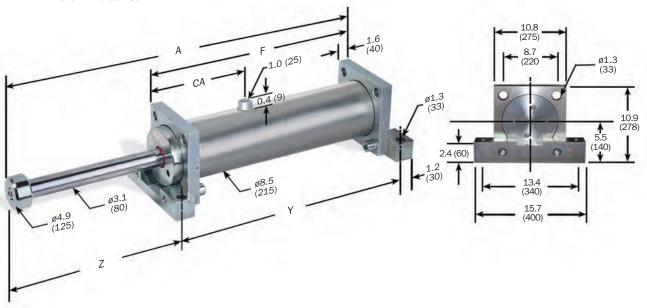
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Heavy Duty Series

HD $5.0 \times 4 \rightarrow HD 5.0 \times 48$ Series

Technical Data



Dimensions are in inches (millimeters).

Note: For TF, FF and FR mounting, delete front foot and dimensions.

Catalog No./ Model	(S) Stroke in. (mm)	(E _T) Max. inlbs./cycle (Nm/cycle)	(E _T C) Max. inlbs./hour (Nm/hr)	(F _P) Max. Shock Force Ibs. (N)	Nominal Return Force BA* Ibs. (N)	A in. (mm)	F in. (mm)	Y in. (mm)	Z in. (mm)	CA in. (mm)	Model Weight Ibs. (Kg)
HD 5.0 x 4	4 (100)	414,000	16,000,000	124,000	400	23.3	14.8	17.1	7.4	9.1	192
	(100)	(46 700)	(1 762 621)	(550 000)	(1 760) 400	(591) 27.3	(37.5)	(435) 19.1	(186) 9.4	(230) 9.1	(87) 207
HD 5.0 x 6	6 (150)	620,000 (70 000)	17,720,000 (2 002 337)	124,000 (550 000)	(1 760)	27.3 (693)	16.8 (426)	(486)	(237)	(230)	(94)
	8	828,000	19,841,000	124,000	400	31.3	18.8	21.1	11.4	9.1	223
HD 5.0 x 8	(200)	(93 500)	(2 242 053)	(550 000)	(1 760)	(795)	(477)	(537)	(288)	(230)	(101)
UD 5 0 10	10	1,036,000	21,921,000	124,000	400	35.3	20.8	23.1	13.4	9.1	238
HD 5.0 x 10	(250)	(117 000)	(2 477 070)	(550 000)	(1 760)	(895)	(527)	(587)	(338)	(230)	(108)
HD 5.0 x 12	12	1,239,000	24,042,000	124,000	400	39.3	22.8	25.1	15.4	9.1	251
ПD 3.0 X 12	(300)	(140 000)	(2 716 786)	(550 000)	(1 760)	(997)	(578)	(638)	(389)	(230)	(114)
HD 5.0 x 16	16	1,655,000	28,285,000	124,000	400	47.3	26.8	29.1	19.4	9.1	282
11D 3.0 X 10	(400)	(187 000)	(3 196 219)	(550 000)	(1 760)	(1 201)	(680)	(740)	(491)	(230)	(128)
HD 5.0 x 20	20	2,071,000	36,688,000	124,000	400	59.2	34.7	37.1	23.3	13.0	348
115 516 X 20	(500)	(234 000)	(4 145 684)	(550 000)	(1 760)	(1 504)	(882)	(942)	(592)	(230)	(158)
HD 5.0 x 24	24	2,478,000	40,930,000	124,000	400	67.2	38.7	41.1	27.3	13.0	377
	(600)	(280 000)	(4 625 117)	(550 000)	(1 760)	(1 708)	(984)	(1 044)	(694)	(230)	(171)
HD 5.0 x 28	28	2,894,000	45,132,000	124,000	400	75.2	42.7	45.1	31.3	13.0	407
	(700)	(327 000)	(5 099 849)	(550 000)	(1 760)	(1 910)	(1 085)	(1 145)	(795)	(230)	(185)
HD 5.0 x 32	32	3,310,000	49,374,000	124,000	400	83.2	46.7	49.1	35.3	13.0	437
	(800) 40	(374 000)	(5 579 282)	(550 000)	(1 760)	(2 114)	(1 187)	(1 247)	(897)	(230)	(198)
HD 5.0 x 40	(1 000)	4,133,000 (467 000)	57,818,000 (6 533 447)	124,000 (550 000)	400 (1 760)	99.2 (2 520)	54.7 (1 390)	57.1	43.3 (1 100)	13.0 (231)	496 (225)
	48	4,750,000	66,262,000	92,000	400	115.0	62.6	65.0	51.6	13.0	534
HD 5.0 x 48	(1 200)	(535 800)	(7 487 613)	(410 000)	(1 760)	(2 920)	(1 590)	(1 650)	(1 300)	(230)	(242)

Notes: 1. HD shock absorbers will function satisfactorily at 5% of their maximum rated energy per cycle.

HDA models will function satisfactorily at 10% of their maximum rated energy per cycle. If less than these values, a smaller model should be specified.

- 2. It is recommended that the customer consult ITT Enidine for safety-related overhead crane applications.
- 3. The energy data listed is for ideal linear impacts only. If side load conditions exist in the application, contact ITT Enidine for sizing assistance.
- 4. Rear flange mounting of 12 inch (300 mm) strokes and longer not recommended. Front and rear flange or foot mount configurations are recommended.

Tel.: 1-800-852-8508

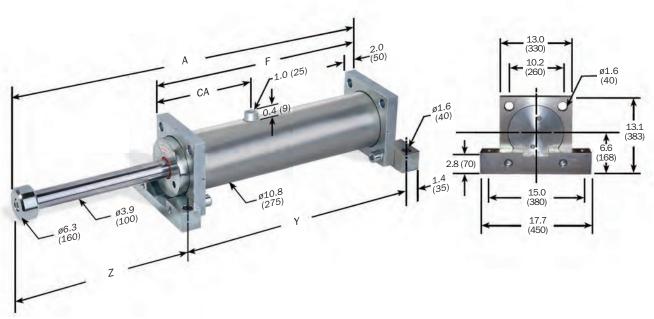
- 5. Maximum cycle rate is 60 cycles/hr.
- 6. For impact velocities over 180 in./sec. (4.5 m/s), consult factory.

ENIDINE

Fax: 1-716-662-0406

Technical Data

HD 6.0 x 4 \rightarrow HD 6.0 x 48 Series



Dimensions are in inches (millimeters).

Note: For TF, FF and FR mounting, delete front foot and dimensions.

Difficitions are in miches	neisions die in niches (minimeleis).								Note. For 1r, Fr and FK mounting, delete from 1001 and annersions.						
Catalog No./ Model	(S) Stroke in. (mm)	(E _T) Max. inlbs./cycle (Nm/cycle)	(E _T C) Max. inlbs./hour (Nm/hr)	(F _P) Max. Shock Force lbs. (N)	Nominal Return Force BA* Ibs. (N)	A in. (mm)	F in. (mm)	Y in. (mm)	Z in. (mm)	CA in. (mm)	Model Weight Ibs. (Kg)				
HD(A) 6.0 x 4	4	677,000	21,280,000	202,250	625	25.1	15.4	18.2	8.3	7.8	362				
пи(а) 6.0 х 4	(100)	(76 500)	(2 404 568)	(900 000)	(2 750)	(637)	(391)	(461)	(211)	(197)	(164)				
HD(A) 6.0 x 6	6	1,010,000	23,933,000	202,250	625	29.1	17.4	20.2	10.3	7.8	386				
пр(А) 0.0 х о	(150)	(114 000)	(2 704 389)	(900 000)	(2 750)	(737)	(441)	(511)	(261)	(197)	(175)				
HD(A) 6.0 x 8	8	1,354,000	26,586,000	202,250	625	33.1	19.4	22.2	12.3	7.8	410				
пь(а) 0.0 х о	(200)	(153 000)	(3 004 211)	(900 000)	(2 750)	(839)	(492)	(562)	(312)	(197)	(186)				
HD(A) 6.0 x 10	10	1,690,000	29,345,000	202,250	625	37.1	21.4	24.2	14.3	7.8	432				
11D(A) 0.0 X 10	(250)	(191 000)	(3 316 025)	(900 000)	(2 750)	(941)	(543)	(613)	(363)	(197)	(196)				
HD(A) 6.0 x 12	12	1,982,000	32,052,000	202,250	625	41.1	23.4	26.2	16.3	7.8	456				
11D(A) 0.0 X 12	(300)	(224 000)	(3 621 843)	(900 000)	(2 750)	(1 043)	(594)	(664)	(414)	(197)	(207)				
HD 6.0 x 16	16	2,708,000	37,465,000	202,250	625	49.1	27.4	30.2	20.3	7.8	503				
11D 0.0 X 10	(400)	(306 000)	(4 233 478)	(900 000)	(2 750)	(1 246)	(696)	(766)	(515)	(197)	(228)				
HD 6.0 x 20	20	3,380,000	42,877,000	202,250	625	57.1	31.4	34.2	24.3	7.8	551				
пр 0.0 x 20	(500)	(382 000)	(4 845 114)	(900 000)	(2 750)	(1 450)	(798)	(868)	(617)	(197)	(250)				
IID 4 0 04	24	4,062,000	53,862,000	202,250	625	69.7	40.0	42.7	28.4	12.3	681				
HD 6.0 x 24	(600)	(459 000)	(6 086 375)	(900 000)	(2 750)	(1 769)	(1 015)	(1 085)	(719)	(312)	(309)				
IID (0 00	30	5,070,000	61,928,000	202,250	625	81.6	46.0	48.7	34.3	12.3	752				
HD 6.0 x 30	(750)	(573 000)	(6 997 832)	(900 000)	(2 750)	(2 073)	(1 167)	(1 237)	(871)	(312)	(341)				
	36	6,093,000	70,047,000	202,250	625	93.7	52.0	54.7	40.4	12.3	822				
HD 6.0 x 36	(900)	(688 500)	(7 915 285)	(900 000)	(2 750)	(2 379)	(1 320)	(1 390)	(1 024)	(312)	(373)				
	42	7,106,000	78,113,000	202,250	625	105.6	58.0	60.7	46.3	12.3	893				
HD 6.0 X 42	(1 050)	(803 000)	(8 826 743)	(900 000)	(2 750)	(2 683)	(1 472)	(1 542)	(1 176)	(312)	(405)				
IID / 0 40	48	8,000,000	86,232,000	178,00	625	117.7	64.0	66.7	52.4	12.3	966				
HD 6.0 x 48	(1 200)	(898 200)	(9 744 196)	(790 000)	(2 750)	(2 989)	(1 625)	(1 695)	(1 329)	(312)	(438)				

Notes: 1. HD shock absorbers will function satisfactorily at 5% of their maximum rated energy per cycle.

- HDA models will function satisfactorily at 10% of their maximum rated energy per cycle. If less than these values, a smaller model should be specified.
- 2. It is recommended that the customer consult ITT Enidine for safety-related overhead crane applications.
- 3. The energy data listed is for ideal linear impacts only. If side load conditions exist in the application, contact ITT Enidine for sizing assistance.
- 4. Rear flange mounting of 12 inch (300 mm) strokes and longer not recommended. Front and rear flange or foot mount configurations are recommended.
- 5. HDA models which have an impact velocity below 30 in./sec (.8 m/sec.), please contact ITT Enidine for sizing assistance.
- 6. Maximum cycle rate is 60 cycles/hr.
- 7. For impact velocities over 180 in./sec. (4.5 m/s), consult factory.



Tel.: 1-800-852-8508

Heavy Duty Series Shock Absorber

Mounting and Accessories for HDN, HD, HDA Series

Mounting and Accessories

Typical mounting methods are shown below. Special mounting requirements can be accommodated upon request.



TM: Rear Flange Front Foot Mount



TF: Front and Rear Flanges



CM: Clevis Mount

FM: Front and Rear Foot Mount

Also shown is optional safety cable, typically used in overhead applications.



FF: Front Flange

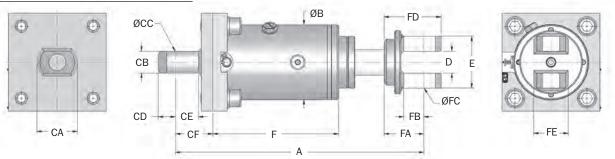


FR: Rear Flange

Note: Rear flange mounting not recommended for stroke lengths above 12 inches. (300 mm)

$HD(A) 3.0 \times 2 \rightarrow HD(A) 4.0 \times 10$ Series

Clevis Mounts (CM)



Dimensions are in inches (millimeters).

Note: Piston clevis dimensions are typical both ends on HD(A) 4.0 models.

Dimensions are in inches (millimet	ers).											NOIR. FISION	ievis ulmensi	ons are typica	i Doin enas	UII IID(A) 4	Illoueis.
								Cyli	ıder Clev	is Dimen	sions		I	Piston Cle	vis Dim	ensions	
Catalog No./ Model	A in. (mm)	B in. (mm)	D in. (mm)	E in. (mm)	HD/HDN F in. (mm)	HDA F in. (mm)	CA in. (mm)	CB in. (mm)	CC in. (mm)	CD in. (mm)	CE in. (mm)	CF in. (mm)	FA in. (mm)	FB in. (mm)	FC in. (mm)	FD in. (mm)	FE in. (mm)
HD(A) 3.0 x 2	17.0 (432)	5.1 (130)	1.5 (38)	3.5 (90)	8.0 (202)	9.3 (235)	2.4 (60)	1.5 (38)	1.0 (25)	1.2 (30)	1.5 (37)	2.6 (65)	2.7 (69)	1.3 (32)	1.0 (25)	3.9 (99)	2.0 (50)
HD(A) 3.0 x 3	19.0 (483)	5.1 (130)	1.5 (38)	3.5 (90)	9.0 (229)	10.3 (261)	2.4 (60)	1.5 (38)	1.0 (25)	1.2 (30)	1.5 (37)	2.6 (65)	2.7 (69)	1.3 (32)	1.0 (25)	3.9 (99)	2.0 (50)
HD(A) 3.0 x 5	23.0 (585)	5.1 (130)	1.5 (38)	3.5 (90)	11.0 (280)	12.3 (312)	2.4 (60)	1.5 (38)	1.0 (25)	1.2 (30)	1.5 (37)	2.6 (65)	2.7 (69)	1.3 (32)	1.0 (25)	3.9 (99)	2.0 (50)
HD(A) 3.0 x 8	29.0 (736)	5.1 (130)	1.5 (38)	3.5 (90)	14.0 (355)	15.2 (387)	2.4 (60)	1.5 (38)	1.0 (25)	1.2 (30)	1.5 (37)	2.6 (65)	2.7 (69)	1.3 (32)	1.0 (25)	3.9 (99)	2.0 (50)
HD(A) 3.0 x 10	330 (838)	5.1 (130)	1.5 (38)	3.5 (90)	16.0 (406)	17.2 (438)	2.4 (60)	1.5 (38)	1.0 (25)	1.2 (30)	1.5 (37)	2.6 (65)	2.7 (69)	1.3 (32)	1.0 (25)	3.9 (99)	2.0 (50)
HD(A) 3.0 x 12	37.0 (940)	5.1 (130)	1.5 (38)	3.5 (90)	18.0 (457)	19.3 (489)	2.4 (60)	1.5 (38)	1.0 (25)	1.2 (30)	1.5 (37)	2.6 (65)	2.7 (69)	1.3 (32)	1.0 (25)	3.9 (99)	2.0 (50)
HD(A) 4.0 x 2	22.4 (570)	7.9 (200)	2.6 (65)	5.5 (140)	11.6 (294)	12.0 (304)	- -	- -	- -	-	- -	3.5 (90)	3.9 (100)	2.4 (60)	2.0 (50)	5.9 (150)	3.9 (100)
HD(A) 4.0 x 4	26.4 (672)	7.9 (200)	2.6 (65)	5.5 (140)	13.6 (345)	14.0 (355)	_ _	- -	_ _	- -	_ _	3.5 (90)	3.9 (100)	2.4 (60)	2.0 (50)	5.9 (150)	3.9 (100)
HD(A) 4.0 x 6	30.4 (772)	7.9 (200)	2.6 (65)	5.5 (140)	15.6 (395)	15.9 (405)	-	-	- -	- -	- -	3.5 (90)	3.9 (100)	2.4 (60)	2.0 (50)	5.9 (150)	3.9 (100)
HD(A) 4.0 x 8	34.4 (875)	7.9 (200)	2.6 (65)	5.5 (140)	17.6 (477)	18.0 (457)	- -	-	- -	- -	- -	3.5 (90)	3.9 (100)	2.4 (60)	2.0 (50)	5.9 (150)	3.9 (100)
HD(A) 4.0 x 10	38.4 (976)	7.9 (200)	2.6 (65)	5.5 (140)	19.6 (497)	20.0 (507)	- -	-	- -	-	-	3.5 (90)	3.9 (100)	2.4 (60)	2.0 (50)	5.9 (150)	3.9 (100)

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ENIDINE

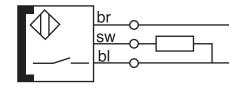
Heavy Duty Series

Mounting and Accessories

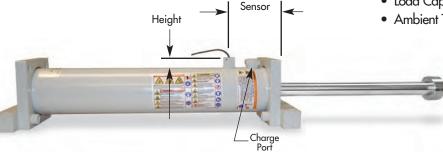
Optional Piston Rod Return Sensor

- Magnetic proximity sensor indicates complete piston rod return with 10-foot (3 m) long cable.
- If complete piston rod does not return the circuit remains open. This can be used to trigger a system shut-off.
- Contact ITT Enidine for other available sensor types.
- Sensor port in line with charge port on models HDN 1.5, 2.0 and 4.0. Location offset 90° for models HDN 3.0 and 3.5.

Sensor Specifications

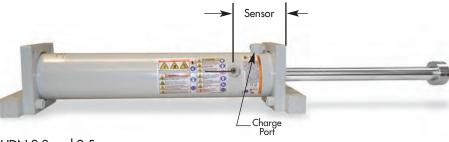


- Voltage 10 30V
- Load Current ≤ 200 mA
- Leakage Current ≤ 80 mA
- Load Capacitance ≤ 1.0 mF
- Ambient Temperature: -15° to 160°F (-26° to 71°C)



NDI	1.5	20	and	40
וטוא	1.5,	2.0	ana	4.0

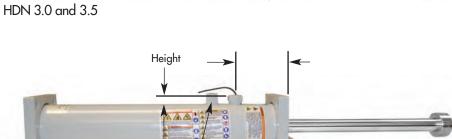
Model	Sensor in. (mm)	Height in. (mm)
HDN 1.5	3.4 (86)	0.79 (20)
HDN 2.0 x 6-28	3.8 (96)	
HDN 2.0 x 32-56	6.9 (176)	0.63 (16)
HDN 4.0 x 2-10	4.3 (108)	0.25 (0)
HDN 4.0 x 12-48	8.0 (202)	0.35 (9)



Model	in. (mm)	in. (mm)
HDN 3.0 x 2-12	2.4 (61)	
HDN 3.0 x 14-32	4.4 (111)	0.59 (15)
HDN 3.0 x 36-60	6.3 (161)	
HDN 3.5 x 2-16	3.0 (77.4)	0.35 (9)
HDN 3.5 x 20-56	5 2 (132 4)	0.33 (7)

Sensor

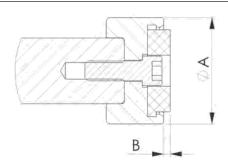
Height



HDN 1.5,	2.0.	3.0.	3.5	and	4.0	BA

Model	Sensor in. (mm)	Height in. (mm)
HDN 1.5	3.4 (86)	0.79 (20)
HDN 2.0 x 6-28	3.8 (96)	0.63 (16)
HDN 2.0 x 32-56	6.9 (176)	0.03 (10)
HDN 3.0 x 2-12	2.4 (61)	
HDN 3.0 x 14-32	4.4 (111)	0.59 (15)
HDN 3.0 x 36-60	6.3 (161)	
HDN 3.5 x 2-16	3.0 (77.4)	
HDN 3.5 x 20-56	5.2 (132.4)	
HDN 4.0 x 2-10	4.3 (108)	0.25 (9)
HDN 4.0 x 12-48	8.0 (202)	

Urethane Cap



Model	Dia. A (mm)	Dia A (in.)	B (mm)	B (in.)
HDN 1.5	60	2.36	4	0.16
HDN 2.0	65	2.56	4	0.16
HDN 3.0	70	2.76	4	0.16

Ordering / Notes

Ordering Example

Note: HDN/HD/HDA models are custom-orificed, therefore all information must be provided to ITT Enidine for unique part number assignment.

Ordering Code Example for Heavy Duty Shock Absorbers

1 - Quantity

2 - Model Selection

HDN (Non-Adjustable)

HD (Non-Adjustable)

HDA (Adjustable)

3 - Model Size

Select Size from Engineering Data Chart

HDN - 1.5, 2.0, 3.0, 3.5, 4.0 Bore Sizes (pages. 8-12)

HDA - 3.0, 4.0 Bore Sizes (pages. 13-14)

HD - 5.0, 6.0 Bore Sizes (pages. 16-17)

4 - Mounting Method

TM (Rear flange front foot mount)

FM (Front and rear foot mount)

TF (Front and rear flanges)

FF (Front flange)

FR (Rear flange)

CM (Metric clevis mount)

5 - Options

C (Sensor cable)

P (Sensor plug) - See Page 18

SC (Safety cable)

BA (Bladder Accumulator)

UC (Urethane Cap)

Application Data (Required for HDN/HD Models)

See Worksheet page 20

Vertical or horizontal motion

Weight

Impact velocity

Propelling force (if any)

Cycles/Hr

Other (temperature or other environmental conditions, safety standards, etc.)

Notes

www.enidine.com

Email: industrialsales@enidine.com

Tel.: 1-800-852-8508

Fax: 1-716-662-0406

Overview



Features and Benefits

- Compact design smoothly and safely decelerates large energy capacity loads up to 4 million in-lbs. per cycle with standard stroke lengths.
- Engineered to meet OSHA, AISE, CMMA and other safety specifications such as DIN and FEM.
- Nitrogen-charged return system allows for soft deceleration and positive return in a maintenance-free package.
- Wide variety of optional configurations including protective bellows and safety cables.

- Available in custom-orificed non-adjustable models.
- Special epoxy painting and rod materials are available for use in highly corrosive environments.
- Surface treatment (Sea water resistant) Housing: gray color, three-part epoxy Piston Rod: hard-chrome plated steel
- Incorporating optional fluids and seal packages available to expand standard operating temperature range from (0°F to 175°F) to (-30°F to 250°F) (-10°C to 60°C) to (-35°C to 100°C)

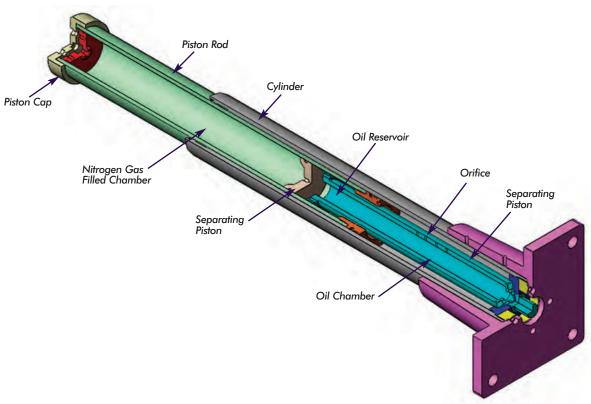
85

Heavy Industry Shock Absorbers

HI Series

Ordering Information

ITT Enidine Heavy Industry (HI) Series Buffers



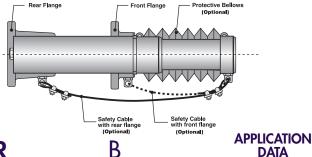
ITT Enidine's Heavy Industry Series (HI) buffers safely protect heavy machinery and equipment during the transfer of materials and movement of products. The large-bore, high-capacity buffers are individually designed to decelerate moving loads under various conditions and in compliance with industry mandated safety standards. Control of bridge cranes, trolley platforms, large container transfer and transportation safety stops are typical installation examples. Industry-proven design technologies, coupled with the experience of a globally installed product base, ensure deliverable performance that exceeds customer expectations.

Prior to HI Series buffer manufacture, computer-simulated response curves are generated to model actual conditions, verify product performance, confirm damping characteristics and generate unique custom-orificed designs that accommodate multi-condition or specific damping requirements.

Characteristics of the HI Series include a nitrogen-charged return system that allows for soft deceleration and positive return in a maintenance-free package. The oversize bore area results in optimal energy absorption capabilities and increased internal safety factors. State-of-the-art testing facilities ensure integrity of design and product performance.

Ordering Example

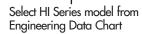
Mounting bracket flange: Standard: Rear or Front mount



Example:



HI 120 x 100



FR

Select mounting method

Tel.: 1-800-852-8508

- FF (Flange Front)
- FR (Flange Rear)

I Additional Options

- B Protective Bellows
- b Projective believ
- C Safety cable

Required for all models:

- Vertical/Horizontal Motion
- Weight

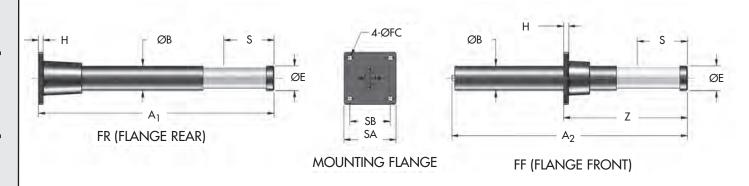
Fax: 1-716-662-0406

- Impact Velocity
- Propelling Force (if any)
- Cycles/Hour
- Temperature/Environment
- Applicable Standards

ENIDINE

HI 50 x 50 → HI 120 x 1000 Series

Technical Data



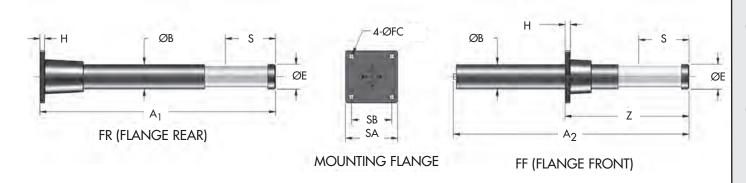
	S	Max.	Max. Shock	Retur	n Force										BOLT	
Catalog No./ Model	Stroke in. (mm)	Energy/cycle inlbs. (Nm)	Force lbs. (kN)	Extension lbs. (kN)	Compression lbs. (kN)	Weight lbs. (Kg)	A ₁ in. (mm)	A ₂ in. (mm)	Z in. (mm)	H in. (mm)	ØB in. (mm)	SA in. (mm)	SB in. (mm)	ØFC in. (mm)	SIZE in. (mm)	ØE in. (mm)
HI 50 x 50	(50)	26,500 (3 000)	15,700 (70)	120 (0,5)	710 (3,2)	11 (5)	10.3 (262)	- -	-	0.6 (15)	2.56 (65)	3.94 (100)	2.76 (70)	0.57 (14,5)	1/2 (M14)	2.28 (58)
HI 50 x 100	3.9 (100)	55,500 (6 200)	15,700 (70)	70 (0,3)	140 (0,6)	20 (9)	15.4	-	-	0.6	2.56	3.94	2.76	0.57	1/ ₂ (M14)	2.28 (58)
ні 85 х 50	2 (50)	60,200 (6 800)	36,000 (160)	225	430 (1,9)	36 (16)	12.8	_	-	0.6 (15)	3.35 (85)	5.04 (128)	3.50	0.79	³ / ₄ (M18)	3.11 (79)
ні 85 х 100	3.9 (100)	120,500 (13 600)	36,000 (160)	225 (1,0)	1,800 (8,0)	49 (22)	16.7	_ _	-	0.6 (15)	3.35 (85)	5.04 (128)	3.50	0.79 (20)	³ / ₄ (M18)	3.11 (79)
ні 100 х 50	2 (50)	88,500 (10 000)	52,800 (235)	370 (1,65)	4,050 (18,0)	36 (16)	11.9 (302)	11.9 (301)	6.9 (175)	0.8 (20)	3.94 (100)	5.91 (150)	4.72 (120)	0.73 (18,5)	5/ ₈ (M16)	3.90 (99)
HI 100 x 100	3.9 (100)	177,000 (20 000)	52,800 (235)	370 (1,65)	4,050 (18,0)	49 (22)	18.9 (479)	18.6 (473)	9.7 (245)	0.8 (20)	3.94 (100)	5.91 (150)	4.72 (120)	0.73 (18,5)	5/8 (M16)	3.90 (99)
HI 100 x 150	5.9 (150)	265,500 (30 000)	52,800 (235)	370 (1,65)	4,050 (18,0)	62 (28)	24.3 (618)	24.1 (612)	11.8 (300)	0.8 (20)	3.94 (100)	5.91 (150)	4.72 (120)	0.73 (18,5)	5/ ₈ (M16)	3.90 (99)
ні 100 х 200	7.9 (200)	354,000 (40 000)	52,800 (235)	370 (1,65)	4,050 (18,0)	71 (32)	29.8 (756)	29.5 (750)	15.4 (390)	0.8 (20)	3.94 (100)	5.91 (150)	4.72 (120)	0.73 (18,5)	5/8 (M16)	3.90 (99)
ні 100 х 400	15.7 (400)	708,060 (80 000)	52,830 (235)	370 (1,65)	4,050 (18,0)	101 (46)	53.1 (1 349)	53.0 (1 345)	25.4 (645)	0.8 (20)	3.94 (100)	5.91 (150)	4.72 (120)	0.73 (18,5)	5/8 (M16)	3.90 (99)
HI 100 x 500	19.7 (500)	831,900 (94 000)	52,800 (235)	370 (1,65)	4,050 (18,0)	115 (52)	_	63.6 (1 616)	35.0 (890)	0.8 (20)	3.94 (100)	5.91 (150)	4.72 (120)	0.73 (18,5)	5/8 (M16)	3.90 (99)
HI 100 x 600	23.6 (600)	991,200 (112 000)	50,000 (220)	370 (1,65)	4,050 (18,0)	128 (58)	_	74.3 (1 888)	40.9	0.8 (20)	3.94 (100)	5.91 (150)	4.72 (120)	0.73 (18,5)	5/8 (M16)	3.90 (99)
ні 100 х 800	31.5 (800)	1,200,000 (136 000)	45,000 (200)	370 (1,65)	4,050 (18,0)	152 (69)	- -	95.5 (2 426)	53.0 (1 345)	0.8 (20)	3.94 (100)	5.91 (150)	4.72 (120)	0.73 (18,5)	5/ ₈ (M16)	3.90 (99)
HI 120 x 100	3.9 (100)	283,200 (32 000)	84,300 (375)	630 (2,8)	11,250 (50,0)	75 (34)	18.5 (471)	18.4 (467)	10.6 (270)	0.8 (20)	4.72 (120)	8.66 (220)	6.69 (170)	1.03 (26,5)	1 (M24)	5.0 (127)
HI 120 x 150	5.9 (150)	424,800 (48 000)	84,300 (375)	630 (2,8)	11,250 (50,0)	86 (39)	23.5 (597)	23.3 (593)	13.0 (330)	0.8 (20)	4.72 (120)	8.66 (220)	6.69 (170)	1.03 (26,5)	1 (M24)	5.0 (127)
HI 120 x 200	7.9 (200)	566,400 (64 000)	84,300 (375)	630 (2,8)	11,250 (50,0)	95 (43)	28.5 (724)	28.3 (720)	15.4 (390)	0.8 (20)	4.72 (120)	8.66 (220)	6.69 (170)	1.03 (26,5)	1 (M24)	5.0 (127)
ні 120 х 300	11.8 (300)	831,900 (94 000)	84,300 (375)	630 (2,8)	11,250 (50,0)	117 (53)	38.3 (973)	38.1 (969)	20.5 (520)	0.8 (20)	4.72 (120)	8.66 (220)	6.69) (170	1.03 (26,5)	1 (M24)	5.0 (127)
HI 120 x 400	15.7 (400)	1,106,300 (125 000)	84,300 (375)	630 (2,8)	11,250 (50,0)	155 (70)	48.2 (1 225)	48.1 (1 221)	26.8 (680)	1.0 (25)	4.72 (120)	8.66 (220)	6.69 (170)	1.03 (26,5)	1 (M24)	5.0 (127)
ні 120 х 600	23.6 (600)	1,663,900 (188 000)	84,300 (375)	630 (2,8)	11,250 (50,0)	232 (105)	-	67.9 (1 725)	36.0 (915)	1.0 (25)	4.72 (120)	8.66 (220)	6.69 (170)	1.03 (26,5)	1 (M24)	5.0 (127)
HI 120 x 800	31.5 (800)	1,991,250 (225 000)	74,200 (330)	630 (2,8)	11,250 (50,0)	243 (110)	_	91.8 (2 332)	50.8	1.0 (25)	4.72 (120)	8.66 (220)	6.69	1.03 (26,5)	1 (M24)	5.0 (127)
HI 120 x 1000	39.4 (1000)	2,301,000 (260 000)	67,400 (300)	630 (2,8)	11,250 (50,0)	256 (116)	- -	111.7 (2 836)	53.5	1.0 (25)	4.72 (120)	8.66 (220)	6.69	1.03 (26,5)	1 (M24)	5.0 (127)

Heavy Industry Shock Absorbers

HI Series

HI 130 x 250 → HI 150 x 1000 Series

Technical Data



	S	Max.	Max. Shock	Retur	n Force										BOLT	
Catalog No./ Model	Stroke in. (mm)	Energy/cycle inlbs. (Nm)	Force lbs. (kN)	Extension lbs. (kN)	Compression lbs. (kN)	Weight lbs. (Kg)	A ₁ in. (mm)	A ₂ in. (mm)	Z in. (mm)	H in. (mm)	ØB in. (mm)	SA in. (mm)	SB in. (mm)	ØFC in. (mm)	SIZE in. (mm)	ØE in. (mm)
HI 130 x 250	9.8 (250)	885,000 (100 000)	106,800 (475)	725 (3,2)	1,300 (50,0)	159 (72)	35.3 (897)	35.2 (894)	21.5 (545)	1.0 (25)	5.12 (130)	10.63 (270)	8.27 (210)	1.03 (26,5)	1 (M24)	5.08 (129)
ні 130 х 300	11.8	1,062,000	106,800	720	1,300	175	40.5	40.4	23.8	1.0	5.12	10.63	8.27	1.03	1	5.08
	(300)	(120 000)	(475)	(3,2)	(50,0)	(79)	(1 029)	(1 025)	(605)	(25)	(130)	(270)	(210)	(26,5)	(M24)	(129)
HI 130 x 400	15.7	1,416,100	106,800	720	1,300	199	50.9	50.8	28.9	1.0	5.12	10.63	8.27	1.03	1	5.08
	(400)	(160 000)	(475)	(3,2)	(50,0)	(90)	(1 293)	(1 289)	(735)	(25)	(130)	(270)	(210)	(26,5)	(M24)	(129)
ні 130 х 600	23.6 (600)	1,858,500 (210 000)	89,900 (400)	720 (3,2)	10,000 (45,0)	263 (119)	_	75.5 (1 917)	41.5 (1 055)	1.0 (25)	5.12 (130)	10.63 (270)	8.27 (210)	1.03 (26,5)	1 (M24)	5.08 (129)
HI 130 x 800	31.5	2,388,500	89,900	720	10,000	309	_	96.3	53.0	1.0	5.12	10.63	8.27	1.03	1	5.08
	(800)	(270 000)	(400)	(3,2)	(45,0)	(140)	_	(2 445)	(1 345)	(25)	(130)	(270)	(210)	(26,5)	(M24)	(129)
HI 150 x 115	4.5	548,700	145,000	1,125	14,750	124	20.3	20.2	12.6	1.0	5.91	10.63	8.27	1.03	1	5.87
	(115)	(62 000)	(645)	(5,0)	(65,7)	(56)	(516)	(513)	(320)	(25)	(150)	(270)	(210)	(26,5)	(M24)	(149)
ні 150 х 150	5.9	725,700	145,000	1,125	14,750	130	23.9	23.7	14.0	1.0	5.91	10.63	8.27	1.03	1	5.87
	(150)	(82 000)	(645)	(5,0)	(65,7)	(59)	(606)	(602)	(355)	(25)	(150)	(270)	(210)	(26,5)	(M24)	(149)
HI 150 x 400	15.7	1,947,000	145,000	1,125	14,000	216	49.5	49.0	28.0	1.0	5.91	10.63	8.27	1.03	1	5.87
	(400)	(220 000)	(645)	(5,0)	(62,4)	(98)	(1 257)	(1 245)	(710)	(25)	(150)	(270)	(210)	(26,5)	(M24)	(149)
ні 150 х 500	19.7 (500)	2,433,900 (275 000)	145,000 (645)	1,125 (5,0)	17,000 (75,5)	243 (110)	-	59.0 (1 498)	30.3 (770)	1.0 (25)	5.91 (150)	10.63 (270)	8.27 (210)	1.03 (26,5)	1 (M24)	5.87 (149)
ні 150 х 600	23.6	2,920,500	145,000	1,125	17,000	265	_	69.0	34.4	1.0	5.91	10.63	8.27	1.03	1	5.87
	(600)	(330 000)	(645)	(5,0)	(75,5)	(120)	_	(1 752)	(875)	(25)	(150)	(270)	(210)	(26,5)	(M24)	(149)
HI 150 x 800	31.5 (800)	3,965,100 (448 000)	144,000 (640)	1,125 (5,0)	15,250 (68,0)	364 (165)	-	93.0 (2 363)	48.8 (1 240)	1.0 (25)	5.91 (150)	10.63 (270)	8.27 (210)	1.03 (26,5)	1 (M24)	5.87 (149)
ні 150 х 1000	39.4	4,513,500	134,900	1,125	13,750	397	_	113.4	62.8	1.0	5.91	10.63	8.27	1.03	1	5.87
	(1000)	(510 000)	(600)	(5,0)	(61,0)	(180)	_	(2 880)	(1 595)	(25)	(150)	(270)	(210)	(26,5)	(M24)	(149)

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	Application worksheet
FAX NO.:	APPLICATION DESCRIPTION
DATE:	
ATTN:	
COMPANY:	
The ITT Enidine Application Worksheet makes shock absorber sizing and selection easier.	
Fax, phone, or mail worksheet data to Enidine headquarters or your nearest ITT Enidine subsidiary/affiliate or distributor. (See catalog back cover for ITT Enidine locations, or visit www.enidine.com for a list of ITT Enidine distributors.)	
Upon ITT Enidine's receipt of this worksheet, you will receive a detailed analysis of your application and product recommendations. (For custom design projects, Enidine representatives will consult with you for specification	Motion Direction (Check One): ☐ Horizontal ☐ Vertical ☐ Up ☐ Incline Angle ————————————————————————————————————
requirements.)	
GENERAL INFORMATION	□ Rotary Horizontal □ Rotary Vertical □ □ □ Down Weight (Min./Max.): (lbs.)(Kg)
CONTACT:	Cycle Rate (cycles/hour)
DEPT/TITLE:	, , , , , , , , , , , , , , , , , , , ,
COMPANY:	Air Cyl: Bore (in.)(mm) Max. Pressure (psi)(bar) Rod Dia. (in.)(mm)
ADDRESS:	☐ Hydraulic Cyl: Bore (in.)(mm) Max. Pressure(psi)(bar) Rod Dia (in.)(mm)
	☐ Motor(hp)(kW) Torque(in-lbs.)(Nm)
TEL: FAX:	Ambient Temp°F (°C)
EMAIL:	Environmental Considerations:
PRODUCTS MANUFACTURED:	
	Number of Shock Absorbers to Stop Load
	Impact Velocity (min./max.) (in./sec.)(m/sec.)
	Shock Absorber Stroke Requirements:(in.)(mm)
	G Load Requirements(G)(m/sec ²)
APPLICATION SKETCHES / NOTES	

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